

LINEAR MOTOR SINGLE-AXIS ROBOTS

PHASER SERIES

| | |
|-------------|---------------------------------|
| YA | Articulated robots |
| LCM | Linear conveyor modules |
| CX | Single-axis robots |
| Robonity | Motor-less single axis actuator |
| TRANSEVO | Compact single-axis robots |
| FLIP-X | Single-axis robots |
| PHASER | Linear motor single-axis robots |
| XY-X | Cartesian robots |
| YK-X | SCARA robots |
| YP-X | Pick & place robots |
| CLEAN | |
| CONTROLLER | |
| INFORMATION | |

CONTENTS

| | |
|-------------------------------------|-----|
| ■ PHASER SPECIFICATION SHEET | 342 |
| ■ Robot ordering method description | 342 |
| ■ Robot ordering method terminology | 343 |
| MF TYPE | |
| MF7/MF7D | 344 |
| MF15/MF15D | 350 |
| MF20/MF20D | 354 |
| MF30/MF30D | 357 |
| MF75/MF75D | 360 |

PHASER SPECIFICATION SHEET

| Type | Size (mm) ^{Note 1} | Model | Carrier | Maximum payload (kg) | Maximum speed (mm/sec.) | Stroke (mm) | Detailed info page |
|---|-----------------------------|-------|---------|----------------------------|-------------------------|--|-----------------------|
| MF type Flat type with core Linear motor specifications | W85 × H80 | MF7 | Single | 10 (7) ^{Note 2} | 2500 | 100 to 4000 (Horizontal) 100 to 2000 (Wall mount) | P.344 |
| | | MF7D | Double | | | 100 to 3800 (Horizontal) 100 to 1800 (Wall mount) | P.344 |
| | W100 × H80 | MF15 | Single | 30 (15) ^{Note 2} | | 100 to 4000 (Horizontal) 100 to 2000 (Wall mount) | P.350 |
| | | MF15D | Double | | | 100 to 3800 (Horizontal) 100 to 1800 (Wall mount) | P.350 |
| | W150 × H80 | MF20 | Single | 40 (20) ^{Note 2} | | 150 to 4050 | P.354 |
| | | MF20D | Double | | | 150 to 3850 | P.354 |
| | | MF30 | Single | 60 (30) ^{Note 2} | | 100 to 4000 | P.357 |
| | | MF30D | Double | | | 150 to 3750 | P.357 |
| | W210 × H100 | MF75 | Single | 160 (75) ^{Note 2} | | 1000 to 4000 | P.360 |
| | | MF75D | Double | | | 680 to 3680 | P.360 |

Note 1. The size shows approximate maximum cross sectional size.

Note 2. When using at the maximum speed, the maximum payload becomes the value in ().

⚠ Precautions for use

■ Handling

- Please be sure to read "PHASER Series Instruction Manual" carefully to have full understanding of its contents before using this product and strictly observe each instruction.
- Dropping or hitting this product may cause it to break. Always handle it carefully.
- Never disassemble this product. Entry of a foreign object will cause deterioration of accuracy.
- This product uses a magnetic type linear scale. Do not bring anything that generates a strong magnetic field near the robot itself as it may cause damage to the linear scale.

■ Installation place and environment

When installing this product, avoid the place where any of the following conditions applies.

- The ambient temperature is outside of the 0 °C to 40 °C range.
- Dielectric powder such as iron powder, dust, moist, salt or organic solvent is produced and flies in the air.
- Strong electric field, strong magnetic field, etc. occur.
- The product is affected by vibration or impact.
- Dewing occurs, or corrosive gas or combustible gas is generated.
- The product is exposed to direct sun or radiant heat.
- A noise source exists in the surrounding area.
- Inspection and cleaning cannot be performed.

■ Safety precaution

- A high performance rare earth magnets are used in the motor section of this product. For this reason, bringing a magnetic response type device or a medical device such as a heart pace maker close to the robot may cause it to malfunction. Be careful not to bring such a device close to the robot.

Robot ordering method description

In the order format for the YAMAHA linear motor single-axis robots PHASER series, the notation (letters/numbers) for the mechanical section is shown linked to the controller section notation.

[Example]

● Mechanical ▶ MF20

- Cable carrier take out direction ▷ RH
- Grease ▷ Standard
- Optional cable carrier for users ▷ S
- Stroke ▷ 550mm
- Origin position ▷ Change (R side)
- Cable length ▷ 3.5m

● Controller ▶ SR1-P

- Regenerative unit ▷ Required
- I/O selection ▷ NPN

● Ordering method

MF20 - RH - S - Z - 550 - 3L - SR1 - P10 - R - N

Mechanical section

Controller section

This page describes using the ordering form for mechanical components.

To find detailed controller information see the controller page.

SR1-P ▶ [P.652](#), TS-P ▶ [P.626](#), RDV-P ▶ [P.640](#)

Mechanical section

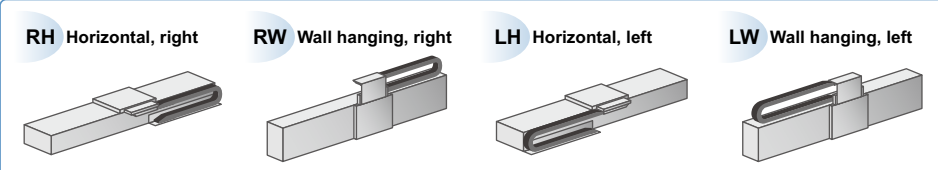
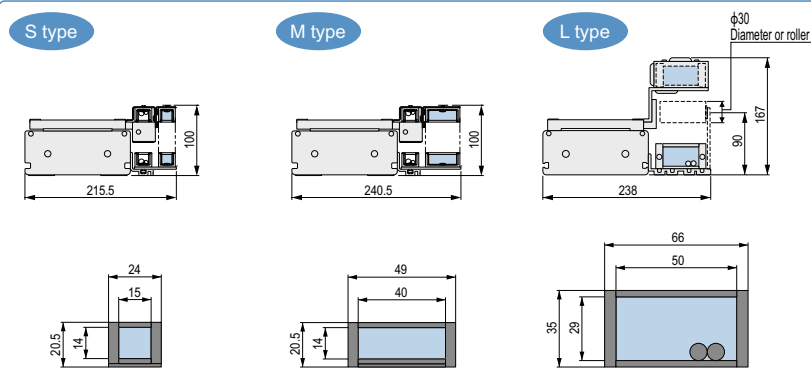
● Single carriage

| ① Model | | ② Cable carrier entry location | ④ Optional cable carrier for users | | ⑤ Origin position change | ⑥ Grease type | | ⑦ Stroke | | ⑧ Cable length | |
|---------|-------|--------------------------------|------------------------------------|--------|--------------------------|---------------|----------|----------|-----|----------------|--|
| MF7 | MF7A | RH Horizontal, right | No entry | None | No entry | L side | No entry | Standard | 3L | 3.5m | |
| MF15 | MF15A | LH Horizontal, left | S | S type | Z | R side | GC | Clean | 5L | 5m | |
| MF20 | MF20A | RW Wall mounted, right | M | M type | | | | | 10L | 10m | |
| MF30 | MF30A | LW Wall mounted, left | L | L type | | | | | 3K | 3.5m | |
| MF75 | MF75A | | | | | | | | 5K | 5m | |
| | | | | | | | | | 10K | 10m | |

● Double carriage

| ① Model | | ③ Installing direction | ④ Optional cable carrier for users | | ⑥ Grease type | | ⑦ Stroke | | ⑧ Cable length | |
|---------|--------|-----------------------------|------------------------------------|--------|---------------|----------|----------|------|----------------|--|
| MF7D | MF7AD | H Horizontal installation | No entry | None | No entry | Standard | 3L | 3.5m | | |
| MF15D | MF15AD | | S | S type | GC | Clean | 5L | 5m | | |
| MF20D | MF20AD | W Wall mounted installation | M | M type | | | 10L | 10m | | |
| MF30D | MF30AD | | L | L type | | | 3K | 3.5m | | |
| MF75D | MF75AD | | | | | | 5K | 5m | | |
| | | | | | | | 10K | 10m | | |

Robot ordering method terminology

| | |
|---|---|
| ① Model | Enter the robot unit model. Select from 2 types: incremental specifications and semi-absolute specifications. |
| ② Cable carrier entry location | Select what direction to install the robot (horizontal / wall mounted) and what direction to extract the robot cable carrier. <div style="text-align: center; margin-top: 10px;"> RH Horizontal, right RW Wall hanging, right LH Horizontal, left LW Wall hanging, left </div>  <p style="font-size: small; margin-top: 10px;">Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.</p> |
| ③ Installing direction | Select what direction to install the robot (horizontal / wall mounted). |
| ④ Optional cable carrier for users | Please specify if a cable carrier is needed for customer wiring. [MF type] (For MF20) <div style="text-align: center; margin-top: 10px;"> S type M type L type </div>  <p style="font-size: x-small; margin-top: 10px;">Cable and pipe guide S : $\phi 8$ flexible cable x 1, $\phi 4$ air tube x 1 M : $\phi 8$ flexible cable x 2, $\phi 6$ air tube x 2 L : $\phi 8$ flexible cable x 2, $\phi 6$ air tube x 3</p> <p style="text-align: right; font-size: x-small;">□ Space for optional cable for users</p> |
| ⑤ Origin position change | Origin point position can be changed. |
| ⑥ Grease type | Clean grease can be selected. |
| ⑦ Stroke | Select the stroke for the robot operating range. |
| ⑧ Cable length | Select the length of the robot cable connecting the robot to the controller. 3L : 3.5m (Standard) 5L : 5m 10L : 10m 3K : 3.5m (Flexible cable) 5K : 5m (Flexible cable) 10K : 10m (Flexible cable) |

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 CLEAN
 CONTROLLER
 INFORMATION

MF7/MF7D

- Flat type available
- Can be used for wall-mount



Ordering method

Single carriage model

MF7

| | | | | | | | | | | |
|---|--|---|---|---|--|--|---|--|---|---|
| Model MF7: Incremental MF7A: Semi-absolute ^{Note 1} | Cable carrier entry location RH: Horizontal, right LH: Horizontal, left FRH: Horizontal, right (Flat) FLH: Horizontal, left (Flat) RW: Wall mount, right LW: Wall mount, left | Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type | Origin position change Horizontal: No entry: L side (Standard) Z: R side Wall: No entry: R side (Standard) Z: L side | Grease type No entry: Standard GC: Clean | Stroke^{Note 3} Horizontal: 100 to 4000 (100mm pitch) S: 5m 100 to 2000 (100mm pitch) Wall: 100 to 2000 (100mm pitch) | Cable length^{Note 4} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 5} | TSP Positioner Note 6 TS-P | Driver: Power-supply voltage / Power capacity 110: 100V/200W 210: 200V/200W | LCD monitor No entry: None L: With LCD | I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 7} |
| | | | | | | | SR1-P Controller | 10 Driver: Power capacity 10: 200W | Usable for CE No entry: Standard E: CE marking | I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS |
| | | | | | | | RDV-P Driver | 2 Power-supply voltage 2: AC200V | 10 Driver: Power capacity 10: 200W or less | RBR1 Regenerative unit |

Note 1. For the details of the semi-absolute model, please refer to P.67. RDV-P has an incremental model only.
 Note 2. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used. Flat type cannot be selected for L type.
 Note 3. Maximum stroke for flat type is 2000mm.
 Note 4. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.732 for details on robot cable.
 Note 5. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
 Note 6. These controllers can be mounted on DIN rails. See P.634 for details.
 Note 7. Select this selection when using the gateway function. For details, see P.96.
 Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.742.

Double carriage model

MF7D

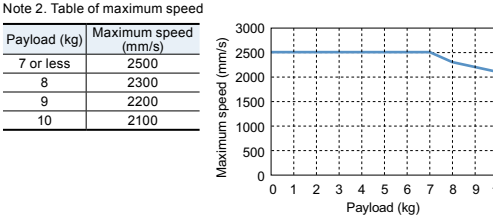
| | | | | | | |
|---|---|---|---|--|---|---|
| Model MF7D: Incremental MF7AD: Semi-absolute ^{Note 1} | Installing direction H: Horizontal installation FH: Horizontal installation (Flat) W: Wall mount installation | Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type | Grease type No entry: Standard GC: Clean | Stroke^{Note 3} Horizontal: 100 to 3800 (100mm pitch) S: 5m 100 to 1800 (100mm pitch) Wall: 100 to 1800 (100mm pitch) | Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 5} | Controller RCX320 RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units) |
|---|---|---|---|--|---|---|

Note. Specify various controller setting items.

Specifications

| Model | MF7 | MF7D |
|--|--|--|
| Driving method | Steel cored linear motor with falt magnet | |
| Repeatability (μm) | +/-5 | |
| Scale (μm) | Magnetic type: resolution of 1 | |
| Maximum speed^{Note 2} (mm/sec) | 2500 | |
| Rated thrust (N) | 37 | |
| Maximum payload (kg) | Horizontal: 10 ^{Note 1} Wall mount: 7 | |
| Stroke (mm) | Horizontal: 100 to 4000 (100mm pitch) Wall mount: 100 to 2000 (100mm pitch) | 100 to 3800 (100mm pitch) 100 to 1800 (100mm pitch) |
| Linear guide | 4 rows of circular arc grooves × 1 rail | |
| Maximum cross-section outside dimensions (mm) | W85 × H80 (except the cable carrier section) | |
| Total length (mm) | Stroke+280 | Stroke+480 |
| Cable length (m) | Standard: 3.5 / Option: 5.10 | |

Note. A vertical model (with brake) is not available with the PHASER series.
 Note. The basic specifications of semi-absolute model are the same as those of the incremental model.
 Note 1. Payload per carrier. When the payload exceeds 7kg, please consult our sales office or sales representative.
 Note 2. Table of maximum speed



Allowable overhang

| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|------|------------------------------------|------|-----|------------------------------|------|------|
| | A | B | C | A | B | C |
| 1kg | 3000 | 3000 | 680 | 700 | 3000 | 3000 |
| 3kg | 3000 | 1350 | 215 | 195 | 1260 | 3000 |
| 5kg | 2900 | 830 | 125 | 90 | 630 | 2480 |
| 7kg | 2400 | 580 | 85 | 50 | 360 | 1680 |
| 9kg | 2200 | 460 | 60 | | | |
| 10kg | 2100 | 410 | 55 | | | |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

| MY | MP | MR |
|-----|-----|-----|
| 156 | 156 | 194 |

(Unit: N·m)

Controller

| Controller | Operating method |
|----------------------------|--|
| SR1-P10 | Programming / I/O point trace / Remote command / Operation using RS-232C communication |
| RCX320 RCX221 RCX340 | |
| TS-P110 | I/O point trace / Remote command |
| TS-P210 | Remote command |
| RDV-P210-RBR1 | Pulse train control |

Cable carrier entry location

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Optional cable carrier for users

Cable and air tube guide
 S: φ8 flexible cable x 1, φ4 air tube x 1
 M: φ8 flexible cable x 2, φ6 air tube x 2
 L: φ8 flexible cable x 2, φ6 air tube x 3

□ Space for optional cable for users

MF7 single carriage horizontal mount model **RH**

Optional cable carrier M type **Optional cable carrier S type**

Detail of section D **Cross-section of E-E**

Cross-section of cable carrier

Table:

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|------------------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 380 | 480 | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 |
| A | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 |
| B | 8 | 10 | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 |
| C | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| Weight (kg) | 5.8 | 6.5 | 7.3 | 8 | 8.7 | 9.4 | 10.1 | 10.9 | 11.6 | 12.3 | 13 | 13.7 | 14.5 | 15.2 | 15.9 | 16.6 | 17.3 | 18.1 | 18.8 | 19.5 |

Notes:
 Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The drawings on this page show the unit with horizontal-right-type cable carrier (RH).
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

MF7 single carriage wall mount model **RW**

Cross-section of optional cable carrier **Cross-section of F-F**

Detail of section G

Standard and S types

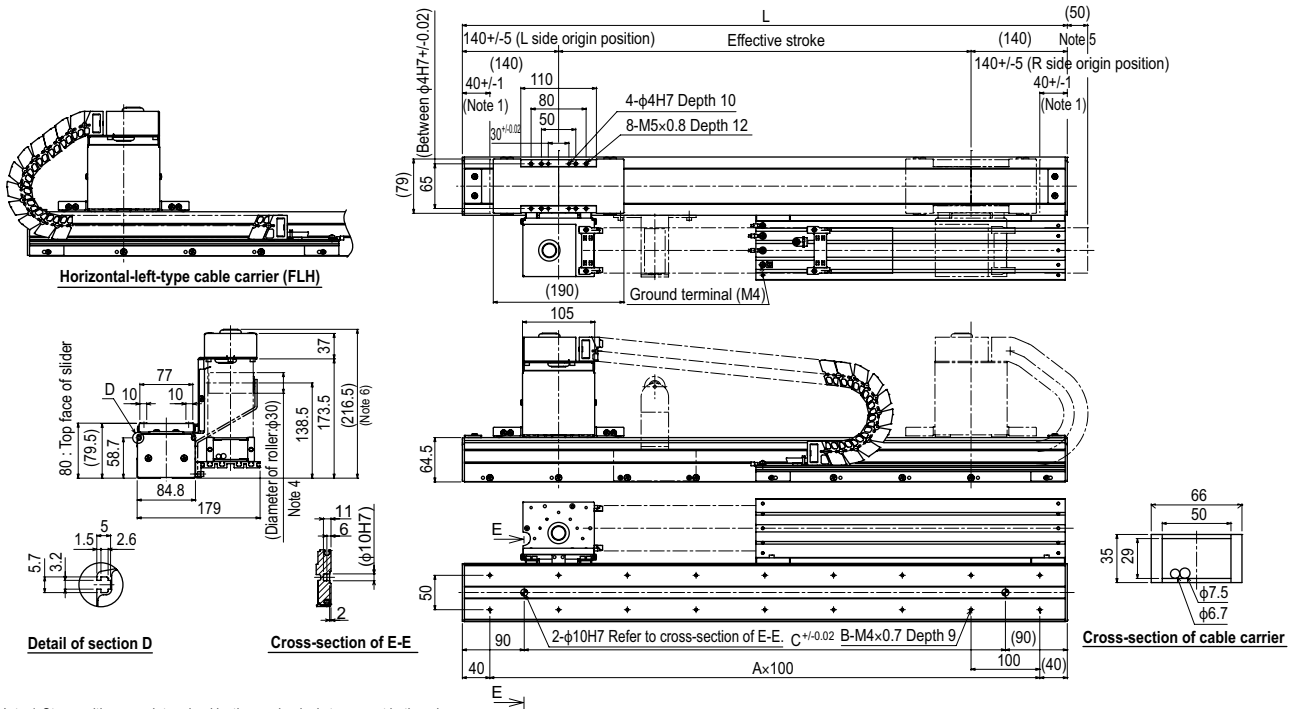
Table:

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|------------------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 380 | 480 | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 |
| A | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 |
| B | 8 | 10 | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 |
| C | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| D | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 | 1120 | 1170 |
| Weight (kg) | 5.8 | 6.5 | 7.3 | 8 | 8.7 | 9.4 | 10.1 | 10.9 | 11.6 | 12.3 | 13 | 13.7 | 14.5 | 15.2 | 15.9 | 16.6 | 17.3 | 18.1 | 18.8 | 19.5 |

Notes:
 Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.
 Note 3. Cable carrier's protrusion amount from the mechanical end (For "L" specs.).
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

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Linear motor single-axis robots
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Cartesian robots
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SCARA robots
YK-X
Pick & place robots
YP-X
CLEAN CONTROLLER INFORMATION

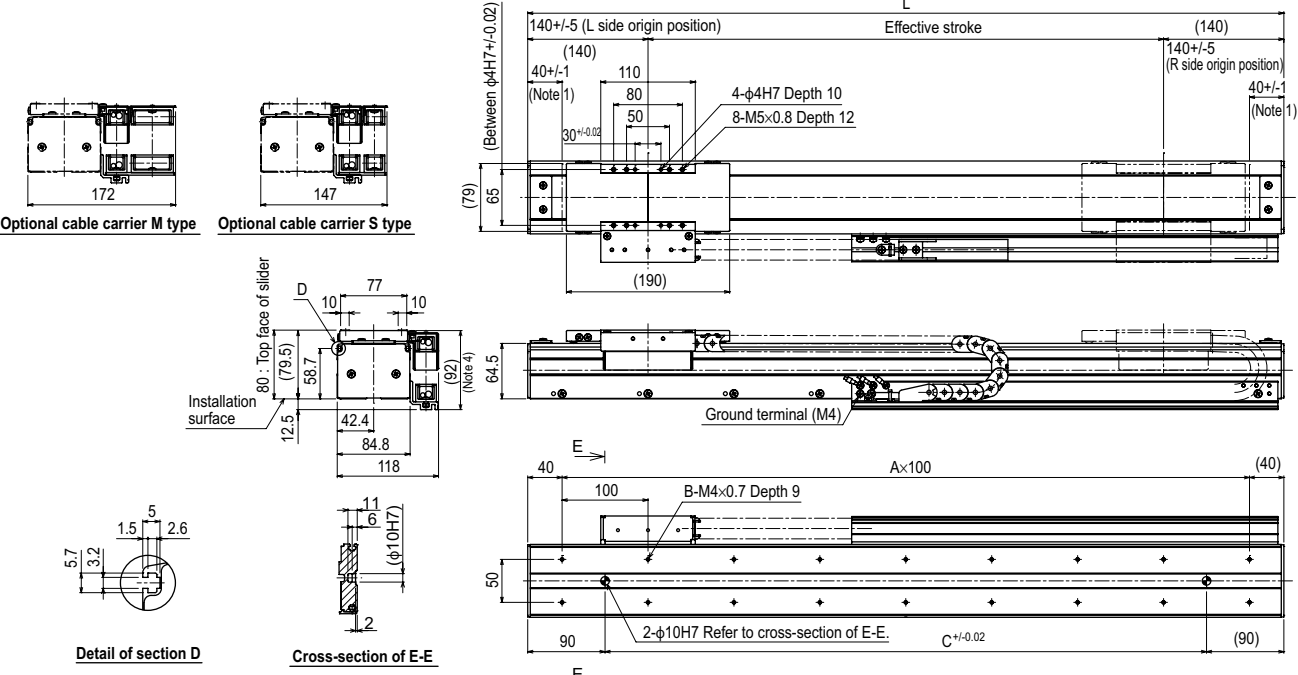
MF7 single carriage horizontal mount model **RH-L** Optional L-type cable carrier



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The drawings on this page show the unit with horizontal-right-type cable carrier (RH).
 Note 4. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. Protrusion is the distance the cable carrier extends from the edge of the unit.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

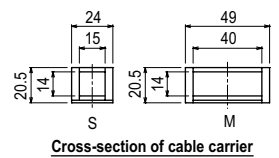
| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 |
|--------------------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 380 | 480 | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 | 2380 | 2480 | 2580 | 2680 | 2780 | 2880 | 2980 | 3080 | 3180 | 3280 | 3380 | 3480 | 3580 | 3680 | 3780 | 3880 | 3980 | 4080 | 4180 | 4280 |
| A | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 |
| B | 8 | 10 | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 | 48 | 50 | 52 | 54 | 56 | 58 | 60 | 62 | 64 | 66 | 68 | 70 | 72 | 74 | 76 | 78 | 80 | 82 | 84 | 86 |
| C | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 |
| Weight (kg) | 5.8 | 6.5 | 7.3 | 8.0 | 8.7 | 9.4 | 10.1 | 10.9 | 11.6 | 12.3 | 13.0 | 13.7 | 14.5 | 15.2 | 15.9 | 16.6 | 17.3 | 18.1 | 18.8 | 19.5 | 20.2 | 20.9 | 21.7 | 22.4 | 23.1 | 23.8 | 24.5 | 25.3 | 26.0 | 26.7 | 27.4 | 28.1 | 28.9 | 29.6 | 30.3 | 31.0 | 31.7 | 32.5 | 33.2 | 33.9 |

MF7 single carriage horizontal mount model **FRH** Flat type



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The drawings on this page show the unit with horizontal-right-type cable carrier (RH).
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|--------------------|-----|-----|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 380 | 480 | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 |
| A | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 |
| B | 8 | 10 | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 |
| C | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| Weight (kg) | 5.8 | 6.5 | 7.3 | 8 | 8.7 | 9.4 | 10.1 | 10.9 | 11.6 | 12.3 | 13 | 13.7 | 14.5 | 15.2 | 15.9 | 16.6 | 17.3 | 18.1 | 18.8 | 19.5 |



Articulated robots
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Single-axis robots
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YK-X

Pick & place robots
YP-X

CLEAN

CONTROLLER INFORMATION

MF7D double carriage horizontal mount model **H**

Optional cable carrier M type **Optional cable carrier S type**

Detail of section D **Cross-section of E-E**

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 | 2380 | 2480 |
| A | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| B | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 | 48 | 50 |
| C | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 |
| Weight (kg) | 9.3 | 10.2 | 11.1 | 12.0 | 12.9 | 13.9 | 14.8 | 15.7 | 16.6 | 17.5 | 18.5 | 19.4 | 20.3 | 21.2 | 22.1 | 23.1 | 24.0 | 24.9 | 25.8 | 26.7 |

MF7D double carriage wall mount model **W**

Cross-section of optional cable carrier **Cross-section of F-F**

Detail of section G

Optional cable carrier L type **Optional cable carrier M type** **Standard and S types**

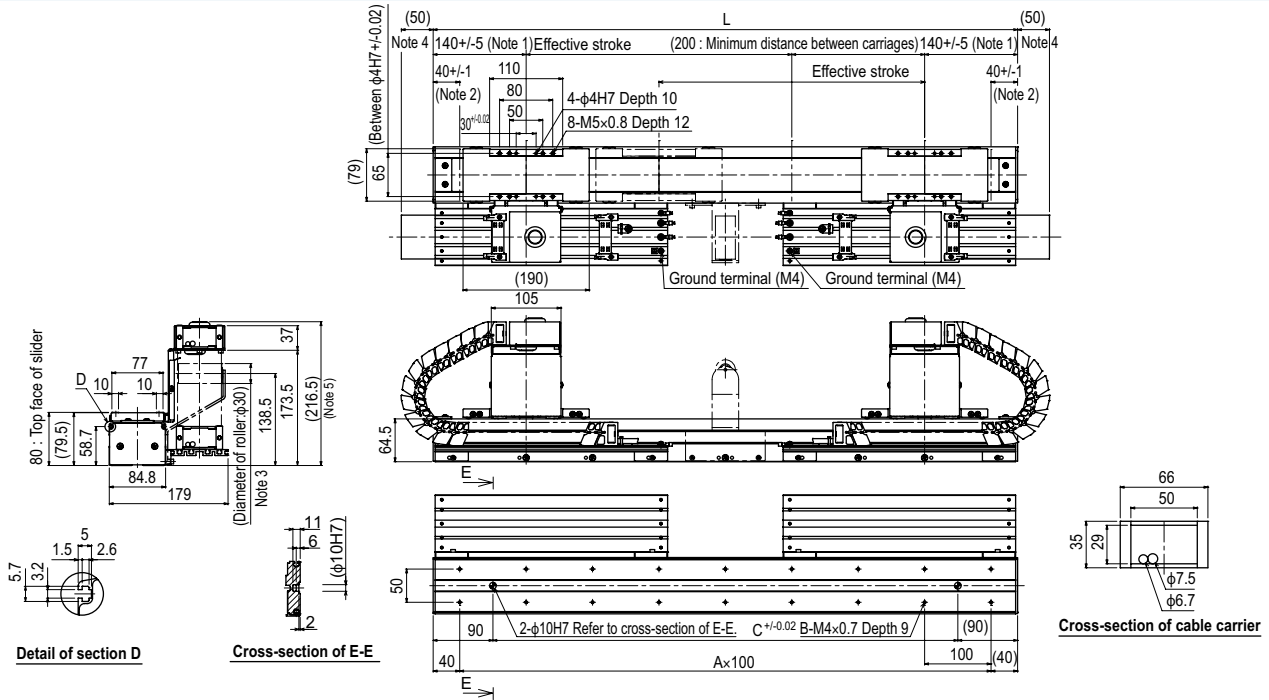
Standard and L types **Standard and M types** **Standard and S types**

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Cable carrier's protrusion amount from the mechanical end.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 |
|------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 |
| A | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 |
| B | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 |
| C | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| D | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 |
| Weight (kg) | 9.3 | 10.2 | 11.1 | 12.0 | 12.9 | 13.9 | 14.8 | 15.7 | 16.6 | 17.5 | 18.5 | 19.4 | 20.3 | 21.2 | 22.1 | 23.1 | 24.0 | 24.9 |

Articulated robots
YA
Linear conveyor modules
LCM
Single-axis robots
CX
Motor-less single axis actuator
Robonity
Compact single-axis robots
TRANSEVO
Single-axis robots
FLIP-X
Linear motor single-axis robots
PHASER

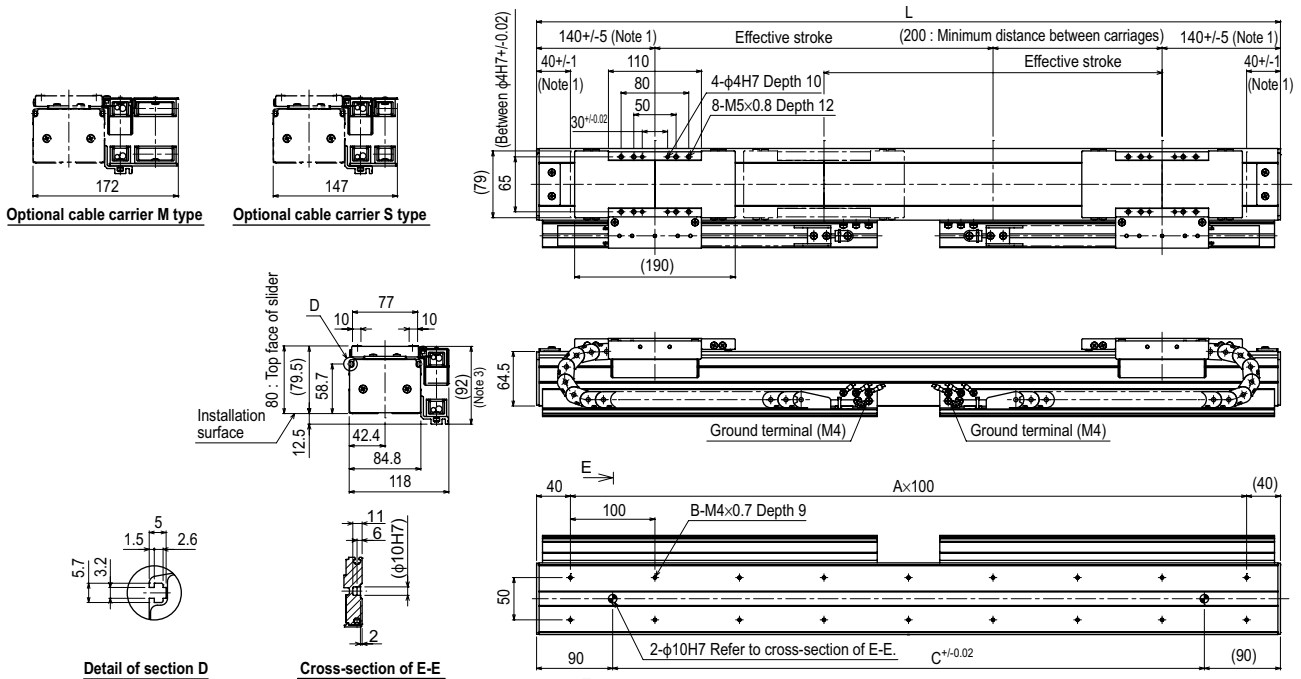
MF7D double carriage horizontal mount model **H-L** Optional L-type cable carrier



Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 4. Protrusion is the distance the cable carrier extends from the edge of the unit.
 Note 5. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 |
|--------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 | 2380 | 2480 | 2580 | 2680 | 2780 | 2880 | 2980 | 3080 | 3180 | 3280 | 3380 | 3480 | 3580 | 3680 | 3780 | 3880 | 3980 | 4080 | 4180 | 4280 |
| A | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 |
| B | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 | 48 | 50 | 52 | 54 | 56 | 58 | 60 | 62 | 64 | 66 | 68 | 70 | 72 | 74 | 76 | 78 | 80 | 82 | 84 | 86 |
| C | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 |
| Weight (kg) | 9.3 | 10.2 | 11.1 | 12.0 | 12.9 | 13.9 | 14.8 | 15.7 | 16.6 | 17.5 | 18.5 | 19.4 | 20.3 | 21.2 | 22.1 | 23.1 | 24.0 | 24.9 | 25.8 | 26.7 | 27.7 | 28.6 | 29.5 | 30.4 | 31.3 | 32.3 | 33.2 | 34.1 | 35.0 | 35.9 | 36.9 | 37.8 | 38.7 | 39.6 | 40.5 | 41.5 | 42.4 | 43.3 |

MF7D double carriage horizontal mount model **FH** Flat type



Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|--------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 580 | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 | 2380 | 2480 |
| A | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| B | 12 | 14 | 16 | 18 | 20 | 22 | 24 | 26 | 28 | 30 | 32 | 34 | 36 | 38 | 40 | 42 | 44 | 46 | 48 | 50 |
| C | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 |
| Weight (kg) | 9.3 | 10.2 | 11.1 | 12.0 | 12.9 | 13.9 | 14.8 | 15.7 | 16.6 | 17.5 | 18.5 | 19.4 | 20.3 | 21.2 | 22.1 | 23.1 | 24.0 | 24.9 | 25.8 | 26.7 |

Articulated robots
YA

Linear conveyor modules
LCM

Single-axis robots
CX

Motor-less single axis actuator
Robonity

Compact single-axis robots
TRANSEVO

Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XY-X

SCARA robots
YK-X

Pick & place robots
YP-X

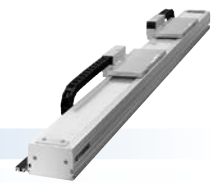
CLEAN

CONTROLLER

INFORMATION

MF15/MF15D

Can be used for wall-mount



Ordering method

Single carriage model

MF15

| | | | | | | | | | | |
|---|---|---|---|---|--|--|--|--|---|---|
| Model MF15: Incremental MF15A: Semi-absolute ^{Note 1} | Cable carrier entry location RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left | Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type | Origin position change Horizontal: No entry: L side (Standard) Z: R side Wall: No entry: R side (Standard) Z: L side | Grease type No entry: Standard GC: Clean | Stroke Horizontal: 100 to 4000 (100mm pitch) 100 to 2000 (100mm pitch) Wall: 100 to 2000 (100mm pitch) | Cable length^{Note 3} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} | TSP Positioner^{Note 5} TS-P | Driver: Power-supply voltage / Power capacity 110: 100V/200W 210: 200V/200W | LCD monitor No entry: None L: With LCD | I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 6} |
|---|---|---|---|---|--|--|--|--|---|---|

SR1-P 10

| | | | |
|-------------------|---|---|---|
| Controller | Driver: Power capacity 10: 200W | Usable for CE No entry: Standard E: CE marking | I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS |
|-------------------|---|---|---|

RDV-P 2 10 RBR1

| | | | |
|---------------|--|---|----------------------------------|
| Driver | Power-supply voltage 2: AC200V | Driver: Power capacity 10: 200W or less | Regenerative unit RBR1 |
|---------------|--|---|----------------------------------|

Note 1. For the details of the semi-absolute model, please refer to P.67. RDV-P has an incremental model only.
 Note 2. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.732 for details on robot cable.
 Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
 Note 5. These controllers can be mounted on DIN rails. See P.634 for details.
 Note 6. Select this selection when using the gateway function. For details, see P.96.
 Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.742.

Double carriage model

MF15D

| | | | | | | |
|---|---|---|---|--|---|---|
| Model MF15D: Incremental MF15AD: Semi-absolute ^{Note 1} | Installing direction H: Horizontal installation W: Wall mount installation | Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type | Grease type No entry: Standard GC: Clean | Stroke Horizontal: 100 to 3800 (100mm pitch) 100 to 1800 (100mm pitch) Wall: 100 to 1800 (100mm pitch) | Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} | Controller RCX320 RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units) |
|---|---|---|---|--|---|---|

Note. Specify various controller setting items.

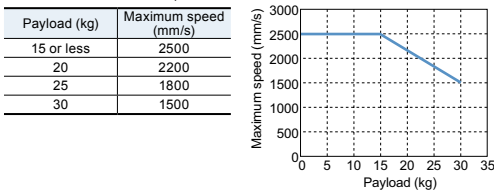
Specifications

| Model | MF15 | MF15D |
|--|---|---|
| Driving method | Steel cored linear motor with falt magnet | |
| Repeatability (µm) | +/-5 | |
| Scale (µm) | Magnetic type: resolution of 1 | |
| Maximum speed^{Note 2} (mm/sec) | 2500 | |
| Rated thrust (N) | 54 | |
| Maximum payload^{Note 1} (kg) | 30 | |
| Stroke (mm) | Horizontal | 100 to 4000 (100mm pitch) / 100 to 3800 (100mm pitch) |
| | Wall mount | 100 to 2000 (100mm pitch) / 100 to 1800 (100mm pitch) |
| Linear guide | 4 rows of circular arc grooves x 2 rail | |
| Maximum cross-section outside dimensions (mm) | W100 x H80 (except the cable carrier section) | |
| Total length (mm) | Stroke+260 | Stroke+460 |
| Cable length (m) | Standard: 3.5 / Option: 5,10 | |

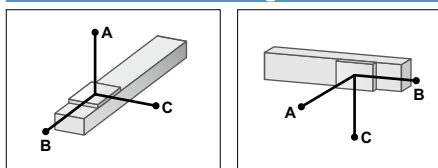
Note. A vertical model (with brake) is not available with the PHASER series. Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

Note 1. Payload per carrier. When the payload exceeds 15kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed



Allowable overhang



Horizontal installation (Unit: mm)

| | A | B | C |
|------|------|------|-----|
| 5kg | 3000 | 3000 | 915 |
| 10kg | 2604 | 1542 | 481 |
| 15kg | 2368 | 1051 | 340 |
| 20kg | 1820 | 600 | 260 |
| 25kg | 1470 | 450 | 175 |
| 30kg | 1250 | 310 | 145 |

Wall installation (Unit: mm)

| | A | B | C |
|------|-----|------|------|
| 5kg | 865 | 1880 | 3060 |
| 10kg | 410 | 905 | 2115 |
| 15kg | 255 | 575 | 1910 |
| 20kg | 170 | 410 | 1780 |
| 25kg | 120 | 295 | 1660 |
| 30kg | 90 | 215 | 1440 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

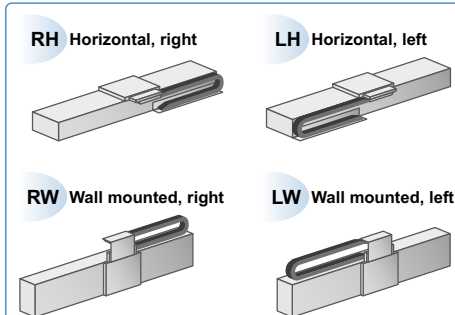
| MY | MP | MR |
|-----|-----|-----|
| 290 | 291 | 256 |

(Unit: N·m)

Controller

| Controller | Operating method |
|----------------------------|--|
| SR1-P10 | Programming / I/O point trace / Remote command / Operation using RS-232C communication |
| RCX320 RCX221 RCX340 | I/O point trace / Remote command |
| TS-P110 TS-P210 | Pulse train control |
| RDV-P210-RBR1 | |

Cable carrier entry location



Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as a special arrangement will be available.

Optional cable carrier for users

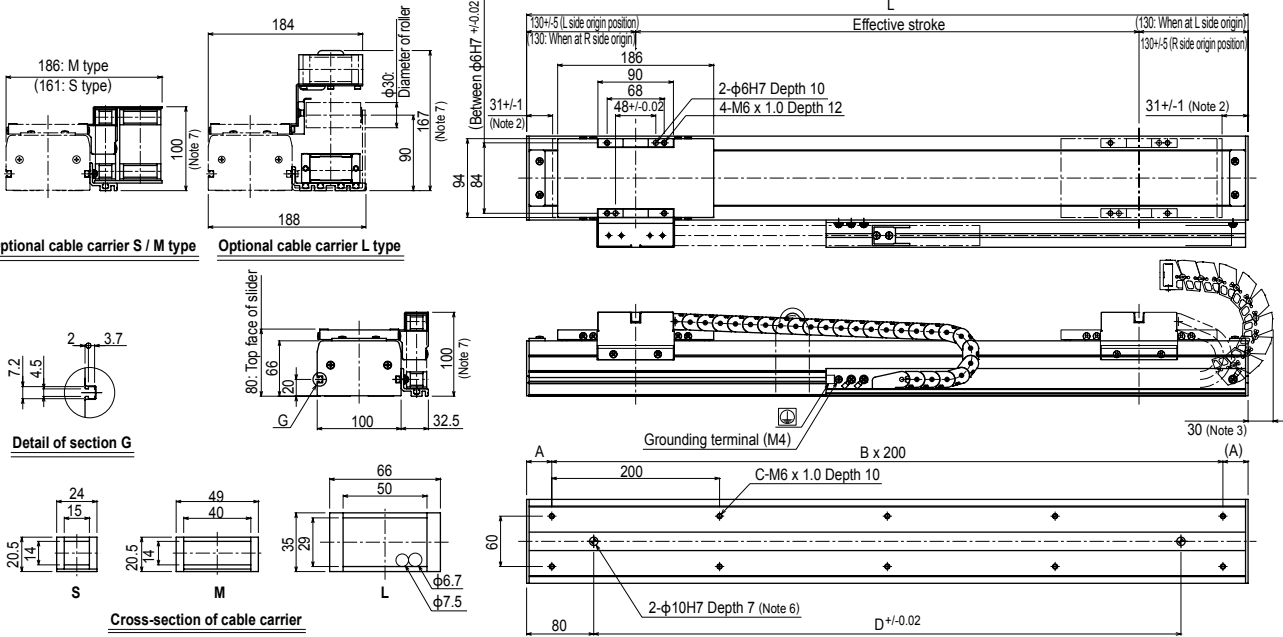
Cable and air tube guide

S: φ8 flexible cable x 1, φ4 air tube x 1
 M: φ8 flexible cable x 2, φ6 air tube x 2
 L: φ8 flexible cable x 2, φ6 air tube x 3

Space for optional cable for users

- Articulated robots
YA
- Linear conveyor modules
LCM
- Single-axis robots
CX
- Motor-less single axis actuator
Robotomy
- Compact single-axis robots
TRANSERO
- Single-axis robots
FLIP-X
- Linear motor single-axis robots
PHASER
- Cartesian robots
XY-X
- SCARA robots
YK-X
- Pick & place robots
YP-X
- CLEAN
- CONTROLLER
- INFORMATION

MF15 single carriage horizontal mount model **(RH)**



Optional cable carrier S / M type

Optional cable carrier L type

Detail of section G

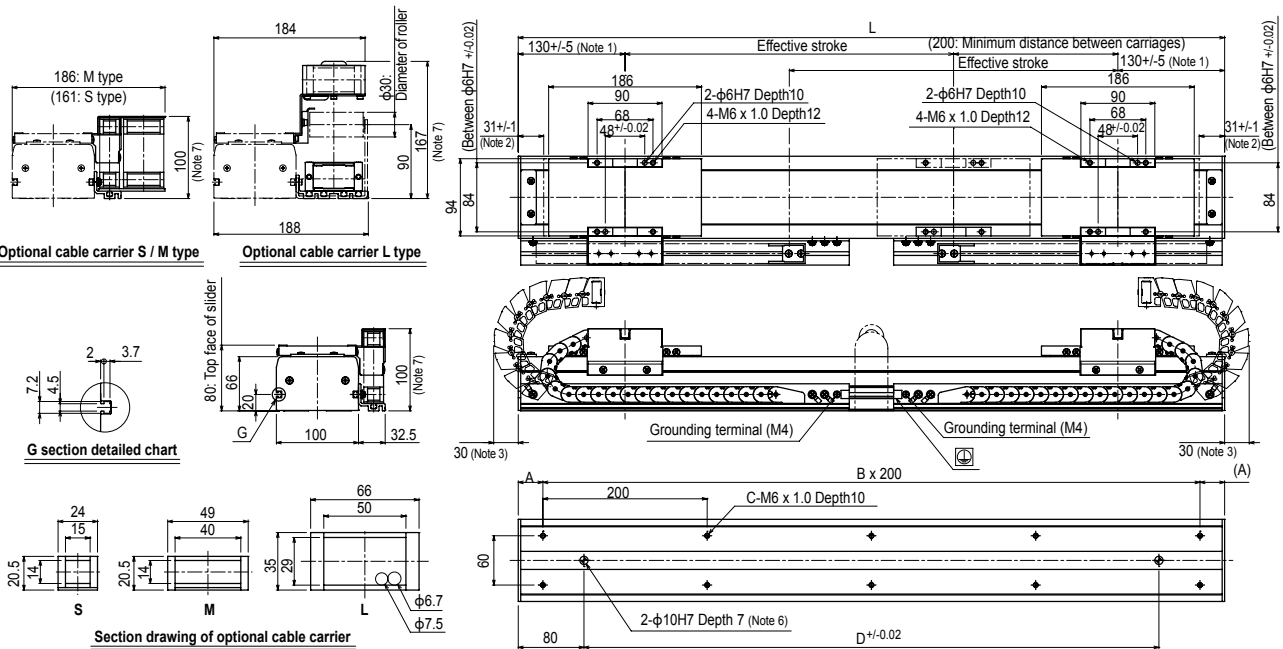
Cross-section of cable carrier

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 4. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.

Note 5. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 |
|------------------|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 360 | 460 | 560 | 660 | 760 | 860 | 960 | 1060 | 1160 | 1260 | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 | 2360 | 2460 | 2560 | 2660 | 2760 | 2860 | 2960 | 3060 | 3160 | 3260 | 3360 | 3460 | 3560 | 3660 | 3760 | 3860 | 3960 | 4060 | 4160 | 4260 |
| A | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 |
| B | 1 | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | |
| C | 4 | 6 | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 |
| D | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 |
| Weight (kg) | 6.3 | 7.3 | 8.3 | 9.3 | 10.3 | 11.3 | 12.3 | 13.3 | 14.3 | 15.4 | 16.4 | 17.4 | 18.4 | 19.4 | 20.4 | 21.4 | 22.4 | 23.4 | 24.4 | 25.4 | 26.4 | 27.4 | 28.4 | 29.4 | 30.4 | 31.4 | 32.4 | 33.4 | 34.4 | 35.4 | 36.4 | 37.4 | 38.4 | 39.4 | 40.4 | 41.4 | 42.4 | 43.4 | 44.4 | 45.4 |

MF15D double carriage horizontal mount model **(H)**



Optional cable carrier S / M type

Optional cable carrier L type

G section detailed chart

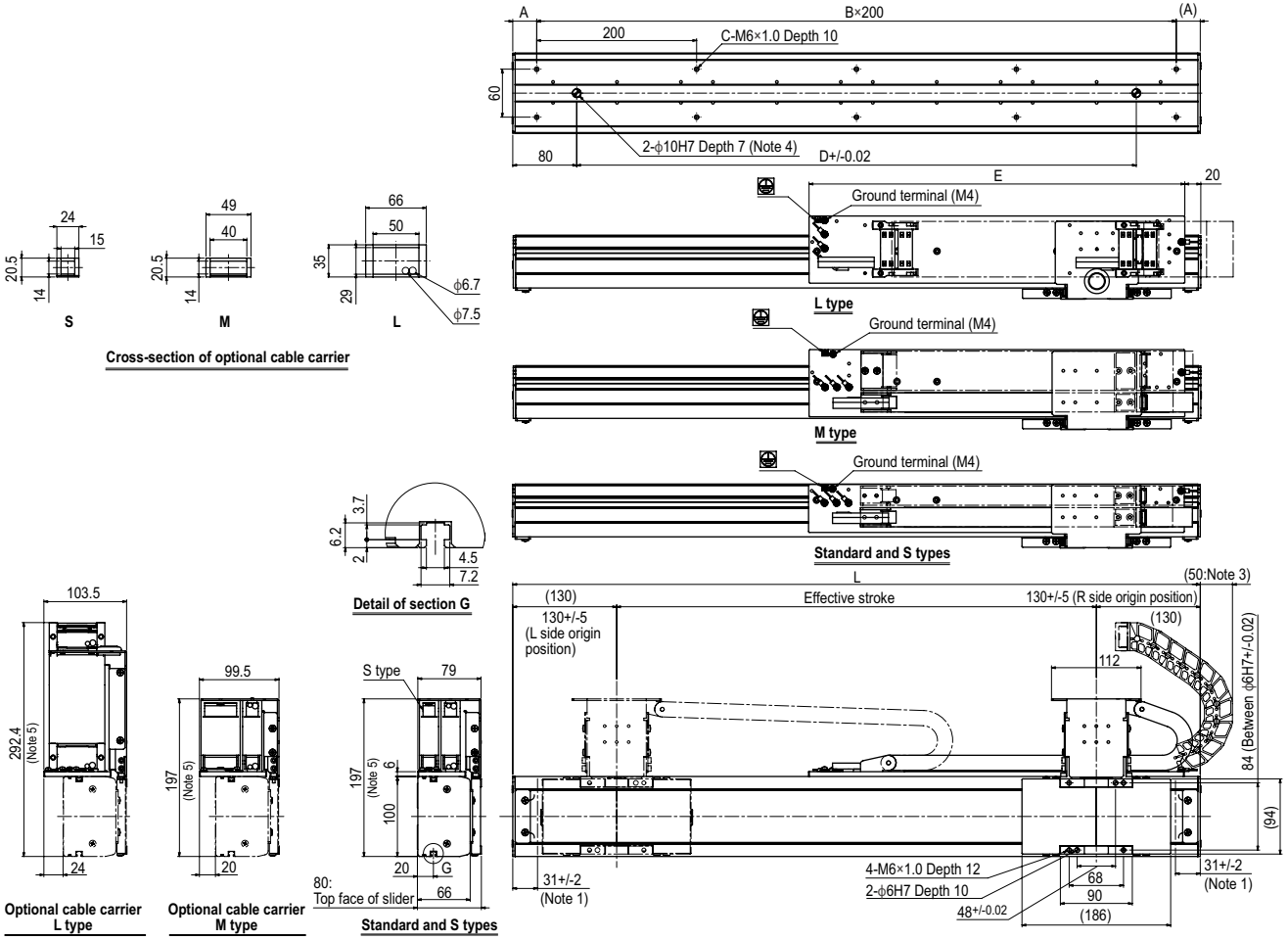
Section drawing of optional cable carrier

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.

Note 4. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 5. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 560 | 660 | 760 | 860 | 960 | 1060 | 1160 | 1260 | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 | 2360 | 2460 | 2560 | 2660 | 2760 | 2860 | 2960 | 3060 | 3160 | 3260 | 3360 | 3460 | 3560 | 3660 | 3760 | 3860 | 3960 | 4060 | 4160 | 4260 | | | |
| A | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | |
| B | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | | | |
| C | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | | | |
| D | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | | |
| Weight (kg) | 10.3 | 11.5 | 12.6 | 13.7 | 14.8 | 16.0 | 17.1 | 18.2 | 19.3 | 20.5 | 21.6 | 22.7 | 23.8 | 25.0 | 26.1 | 27.2 | 28.3 | 29.5 | 30.6 | 31.7 | 32.8 | 33.9 | 35.1 | 36.2 | 37.3 | 38.5 | 39.6 | 40.7 | 41.9 | 43.0 | 44.2 | 45.3 | 46.5 | 47.7 | 48.8 | 50.0 | 51.2 | 52.3 | | | |

MF15 single carriage wall mount model RW

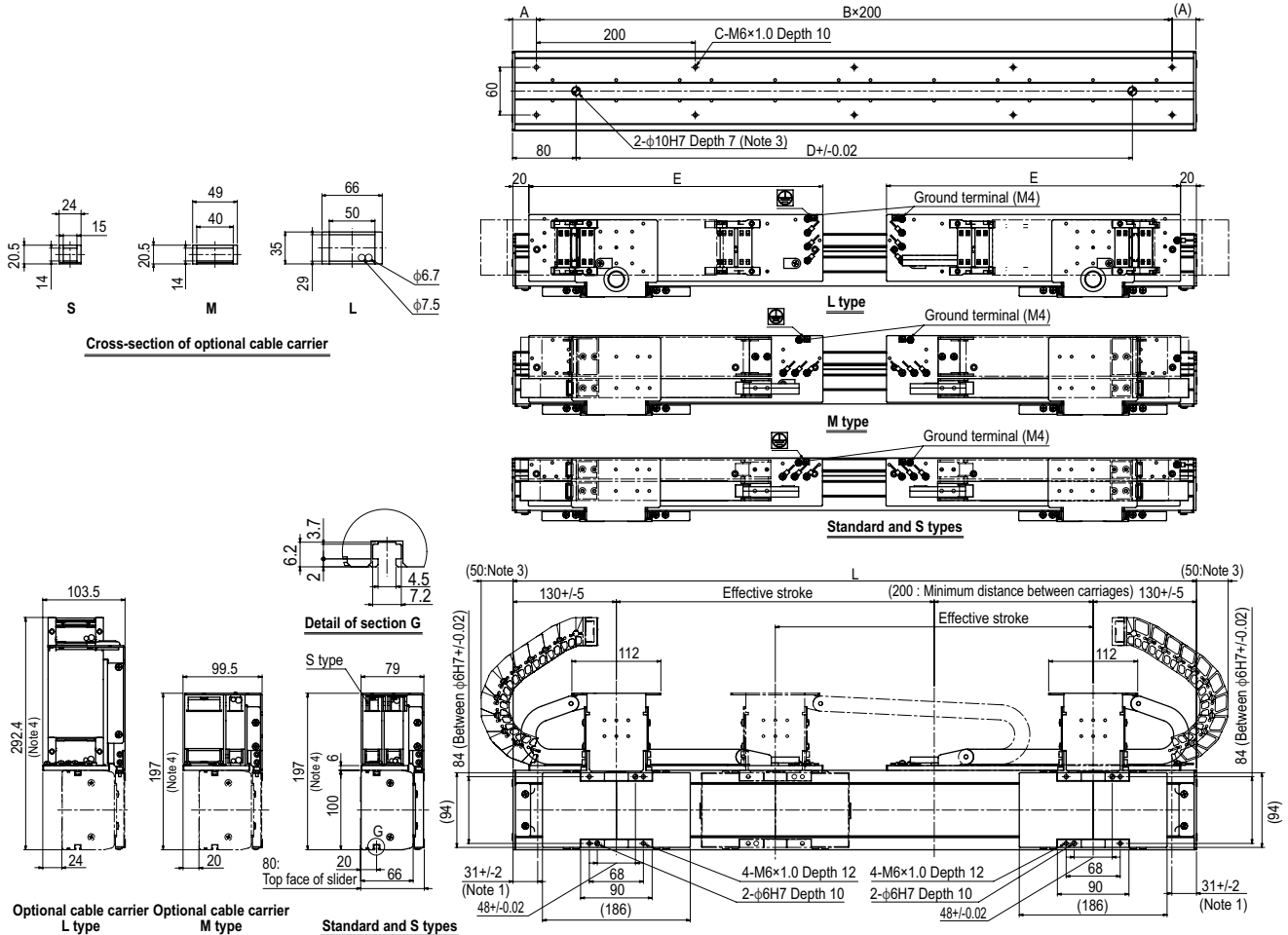


Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.
 Note 3. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 4. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 5. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 |
|------------------|-----|-----|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 360 | 460 | 560 | 660 | 760 | 860 | 960 | 1060 | 1160 | 1260 | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 |
| A | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 |
| B | 1 | 2 | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 |
| C | 4 | 6 | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 |
| D | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| E | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 | 1120 | 1170 |
| Weight (kg) | 6.3 | 7.3 | 8.3 | 9.3 | 10.3 | 11.3 | 12.3 | 13.3 | 14.3 | 15.4 | 16.4 | 17.4 | 18.4 | 19.4 | 20.4 | 21.4 | 22.4 | 23.4 | 24.4 | 25.4 |

MF15D double carriage wall mount model

W



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 3. When using $\phi 10 H7$ hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 560 | 660 | 760 | 860 | 960 | 1060 | 1160 | 1260 | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 |
| A | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 | 80 | 30 |
| B | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 |
| C | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 |
| D | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 |
| E | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 |
| Weight (kg) | 10.3 | 11.5 | 12.6 | 13.7 | 14.8 | 16.0 | 17.1 | 18.2 | 19.3 | 20.5 | 21.6 | 22.7 | 23.8 | 25.0 | 26.1 | 27.2 | 28.3 | 29.5 |

Articulated robots
YA

Linear conveyor modules
LCM

Single-axis robots
CX

Motor-less single axis actuator
Robomity

Compact single-axis robots
TRANSERO

Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XY-X

SCARA robots
YK-X

Pick & place robots
YP-X

CLEAN

CONTROLLER

INFORMATION

MF20/MF20D

Can be used for wall-mount



Ordering method

Single carriage model

MF20

| Model | Cable carrier entry location | Optional cable carrier for users ^{Note 2} | Origin position change | Grease type | Stroke | Cable length |
|---|--|---|--|---------------------------------|---------------------------|--|
| MF20: Incremental MF20A: Semi-absolute ^{Note 1} | RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left | No entry: None S: S type M: M type L: L type | Horizontal No entry: L side (Standard) Z: R side No entry: R side (Standard) Z: L side | No entry: Standard GC: Clean | 150 to 4050 (100mm pitch) | 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} |

TSP

| Positioner ^{Note 5} | Driver: Power-supply voltage / Power capacity | Regenerative unit | LCD monitor | I/O selection |
|------------------------------|---|-------------------|-------------------------------|--|
| TS-P | 110: 100V/200W 210: 200V/200W | R: With RGT | No entry: None L: With LCD | N: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 6} |

SR1-P 10

| Controller | Driver: Power capacity | Usable for CE | Regenerative unit | I/O selection |
|------------|------------------------|-------------------------------------|-------------------|---|
| | 10: 200W | No entry: Standard E: CE marking | R: With RGT1 | N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS |

RDV-P 2 10 RBR1

| Driver | Power-supply voltage | Driver: Power capacity | Regenerative unit |
|--------|----------------------|------------------------|-------------------|
| | 2: AC200V | 10: 200W or less | |

- Note 1. For the details of the semi-absolute model, please refer to P.67. RDV-P has an incremental model only.
- Note 2. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
- Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.732 for details on robot cable.
- Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 5. These controllers can be mounted on DIN rails. See P.634 for details.
- Note 6. Select this selection when using the gateway function. For details, see P.96.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.742.

Double carriage model

MF20D

| Model | Installing direction | Optional cable carrier for users ^{Note 2} | Grease type | Stroke | Cable length | Controller |
|---|--|---|---------------------------------|---------------------------|--|--|
| MF20D: Incremental MF20AD: Semi-absolute ^{Note 1} | H: Horizontal installation W: Wall mount installation | No entry: None S: S type M: M type L: L type | No entry: Standard GC: Clean | 150 to 3850 (100mm pitch) | 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} | RCX320 RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units) |

Note. Specify various controller setting items.

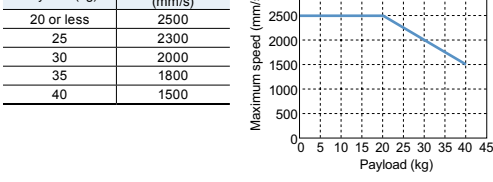
Specifications

| Model | MF20 | MF20D |
|---|---|---------------------------|
| Driving method | Steel cored linear motor with falt magnet | |
| Repeatability (µm) | +/-5 | |
| Scale (µm) | Magnetic type: resolution of 1 | |
| Maximum speed ^{Note 2} (mm/sec) | 2500 | |
| Rated thrust (N) | 86 | |
| Maximum payload ^{Note 1} (kg) | 40 | |
| Stroke (mm) | 150 to 4050 (100mm pitch) | 150 to 3850 (100mm pitch) |
| Linear guide | 4 rows of circular arc grooves x 2 rail W150 x H80 | |
| Maximum cross-section outside dimensions (mm) | (except the cable carrier section) | |
| Total length (mm) | Stroke+260 | Stroke+460 |
| Cable length (m) | Standard: 3.5 / Option: 5.10 | |

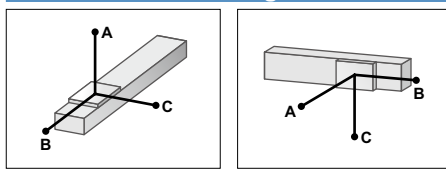
Note. A vertical model (with brake) is not available with the PHASER series.
Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

Note 1. Payload per carrier. When the payload exceeds 20kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed



Allowable overhang



| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | | |
|------|------------------------------------|------|------|------------------------------|------|------|------|
| | A | B | C | A | B | C | |
| 10kg | 3156 | 1747 | 1196 | 10kg | 1220 | 1320 | 2540 |
| 15kg | 2811 | 1176 | 883 | 15kg | 870 | 850 | 2200 |
| 20kg | 2679 | 890 | 717 | 20kg | 670 | 610 | 2030 |
| 25kg | 2190 | 720 | 505 | 25kg | 485 | 400 | 1280 |
| 30kg | 1830 | 605 | 370 | 30kg | 350 | 325 | 1050 |
| 35kg | 1580 | 525 | 275 | 35kg | 265 | 270 | 890 |
| 40kg | 1390 | 465 | 225 | 40kg | 235 | 230 | 765 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

| MY | MP | MR |
|-----|-----|-----|
| 373 | 373 | 328 |

(Unit: N·m)

Controller

| Controller | Operating method |
|--------------------------------|--|
| SR1-P10-R | Programming / I/O point trace / Remote command / Operation using RS-232C communication |
| RCX320-R RCX221-R RCX340 | I/O point trace / Remote command |
| TS-P110-R TS-P210-R | Pulse train control |
| RDV-P210-RBR1 | |

Cable carrier entry location

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

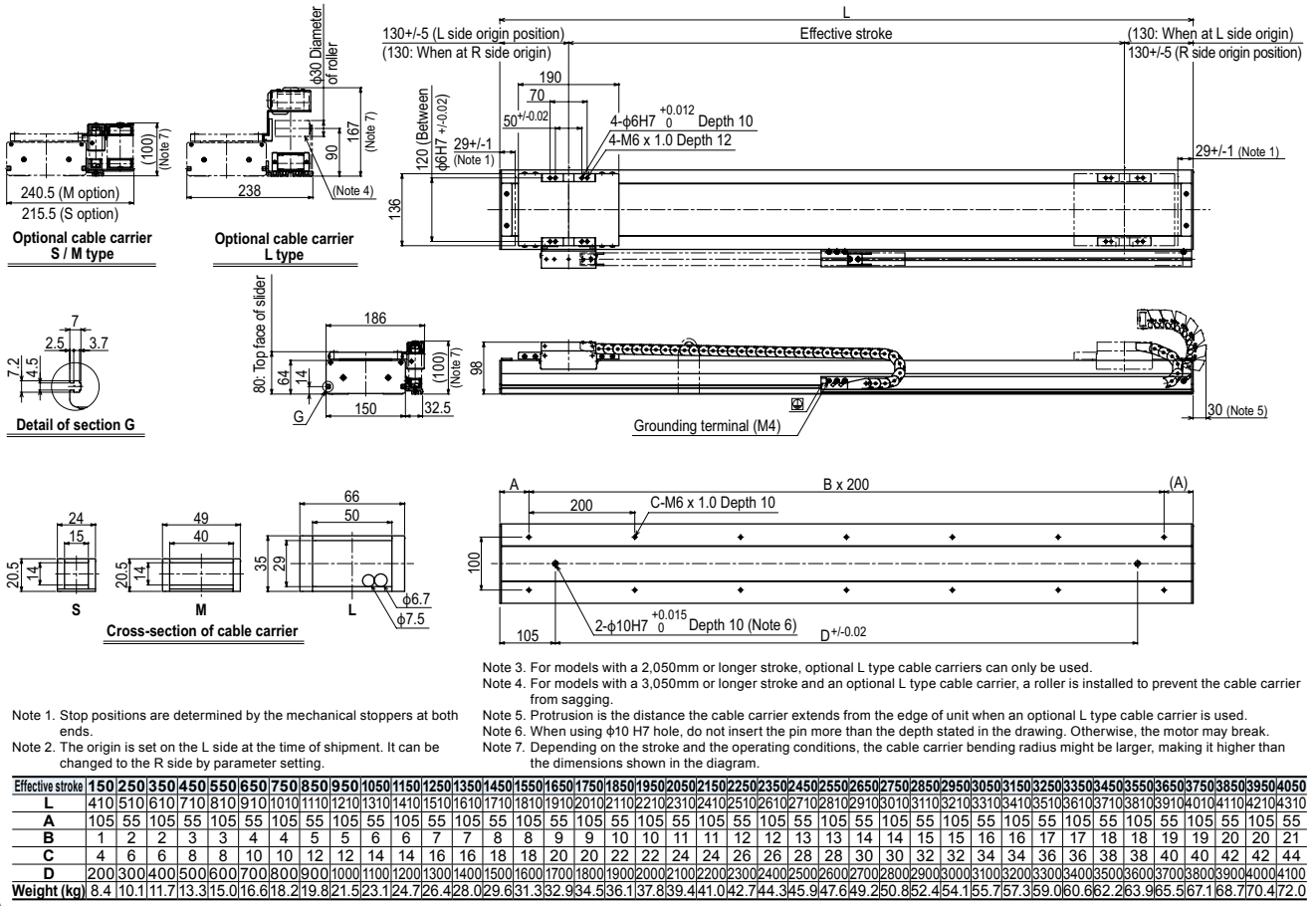
Optional cable carrier for users

Cable and air tube guide

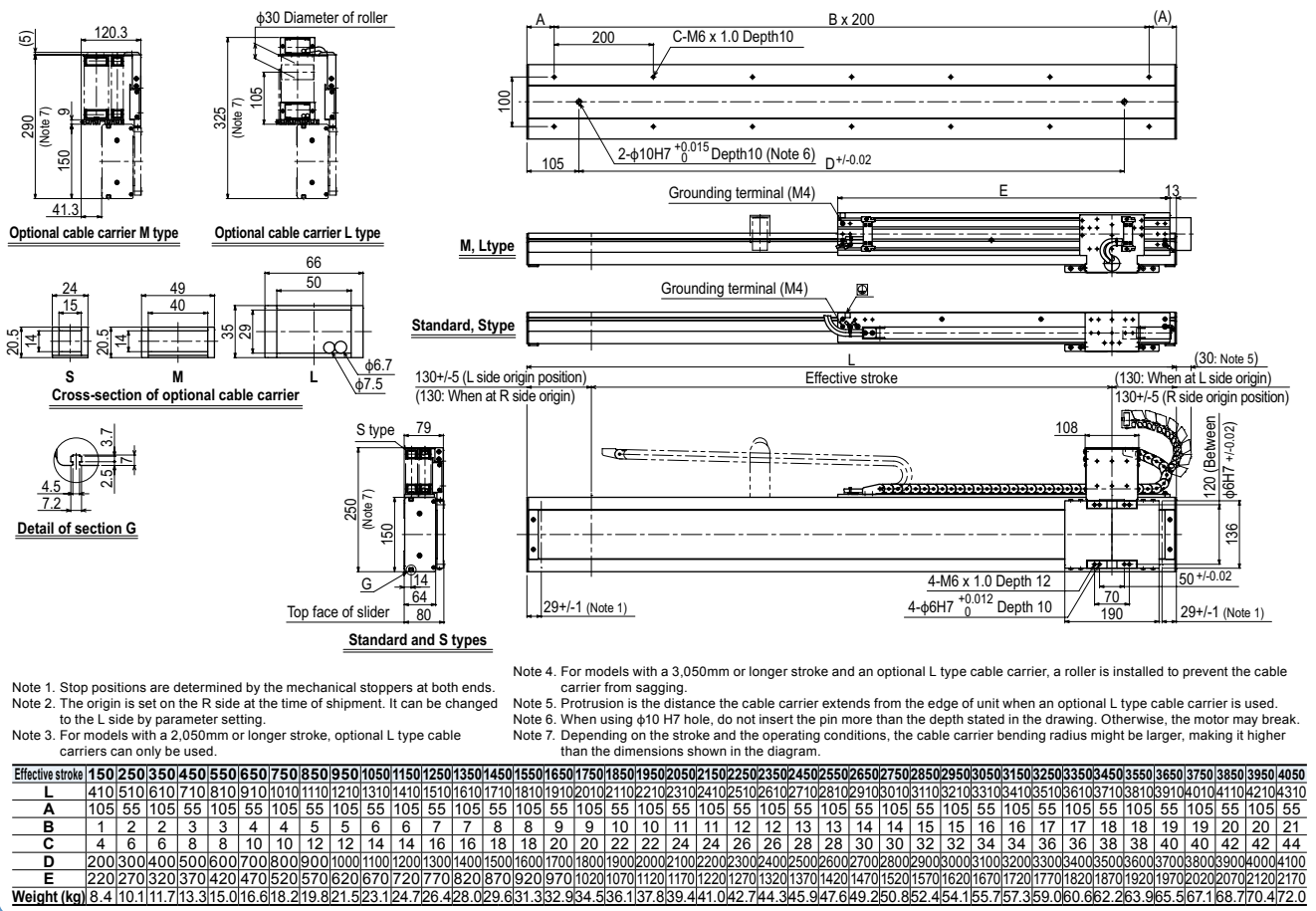
S: φ8 flexible cable x 1, φ4 air tube x 1
M: φ8 flexible cable x 2, φ6 air tube x 2
L: φ8 flexible cable x 2, φ6 air tube x 3

Space for optional cable for users

MF20 single carriage horizontal mount model **RH**

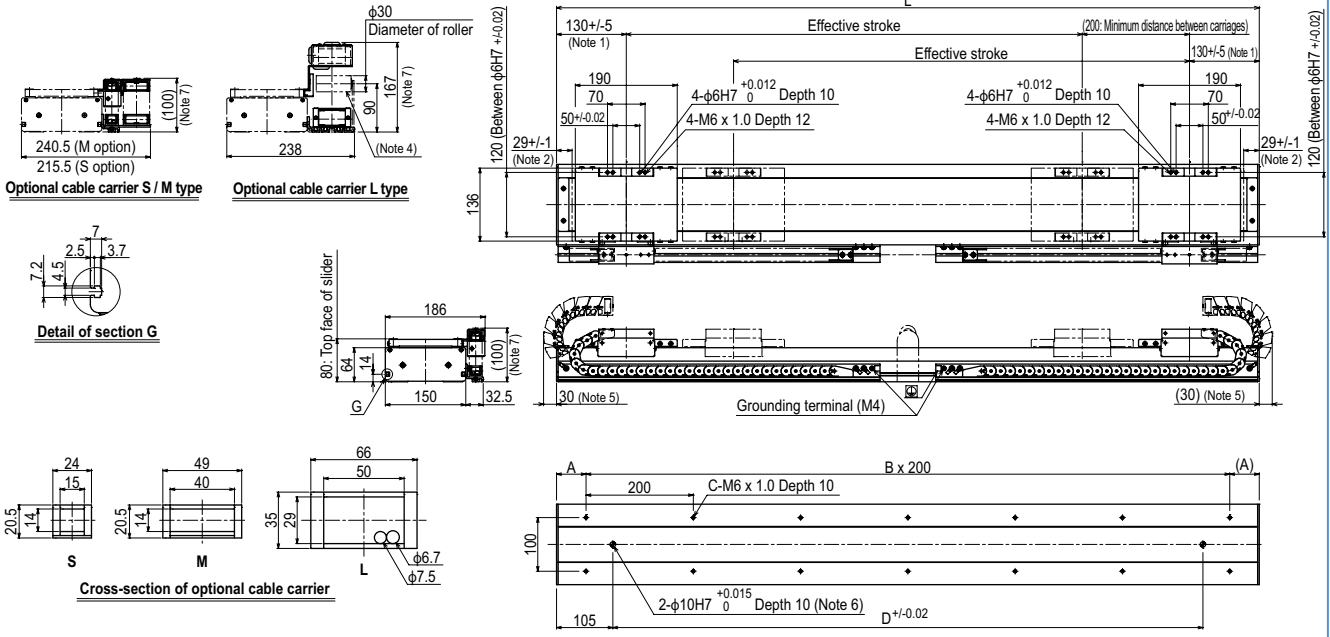


MF20 single carriage wall mount model **RW**



Articulated robots
YA
Linear conveyor modules
LCM
Single-axis robots
CX
Motor-less single axis actuator
Robonity
Compact single-axis robots
TRANSEVO
Single-axis robots
FLIP-X
Linear motor single-axis robots
PHASER
Cartesian robots
XY-X
SCARA robots
YK-X
Pick & place robots
YP-X
CLEAN CONTROLLER INFORMATION

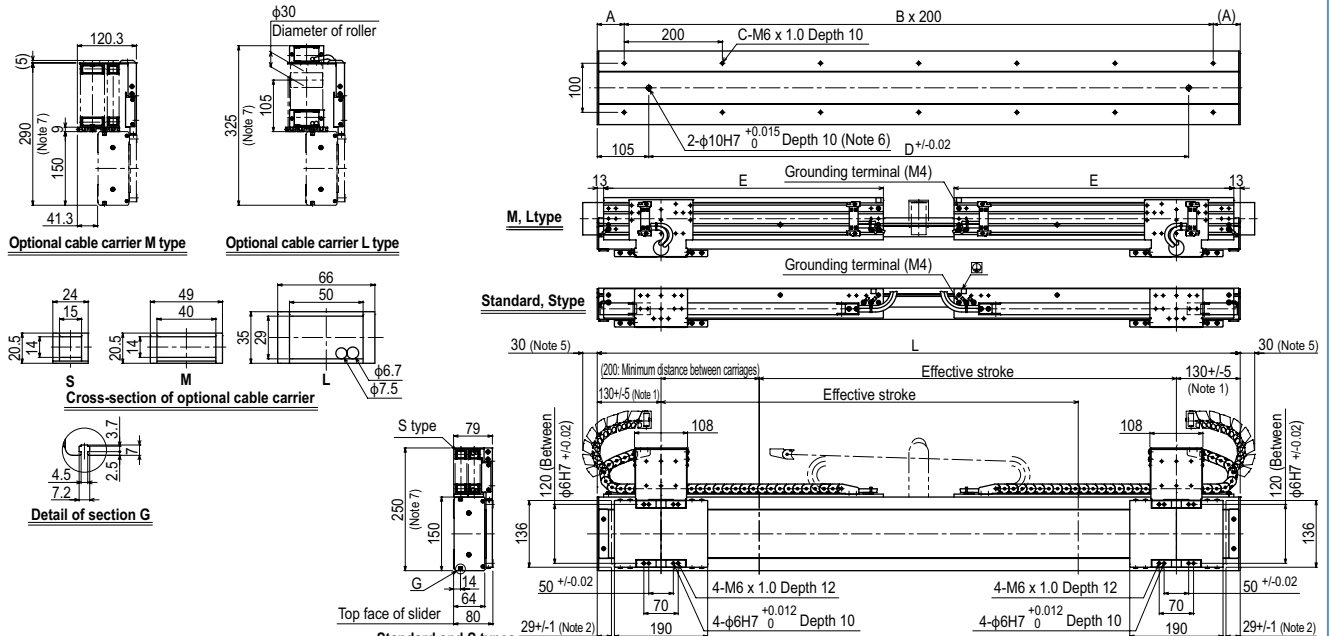
MF20D double carriage horizontal mount model H



Note 1. Position of table carriage when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 150 | 250 | 350 | 450 | 550 | 650 | 750 | 850 | 950 | 1050 | 1150 | 1250 | 1350 | 1450 | 1550 | 1650 | 1750 | 1850 | 1950 | 2050 | 2150 | 2250 | 2350 | 2450 | 2550 | 2650 | 2750 | 2850 | 2950 | 3050 | 3150 | 3250 | 3350 | 3450 | 3550 | 3650 | 3750 | 3850 | | |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-----|----|
| L | 610 | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3110 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | |
| Weight (kg) | 14.9 | 16.6 | 18.3 | 20.0 | 21.7 | 23.5 | 25.2 | 26.9 | 28.6 | 30.3 | 32.0 | 33.7 | 35.4 | 37.1 | 38.8 | 40.5 | 42.2 | 43.9 | 45.6 | 47.3 | 49.0 | 50.7 | 52.4 | 54.1 | 55.8 | 57.5 | 59.2 | 60.9 | 62.6 | 64.3 | 66.0 | 67.7 | 69.4 | 71.1 | 72.8 | 74.5 | 76.2 | 77.9 | | |

MF20D double carriage wall mount model W



Note 1. Position of table carriage when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 150 | 250 | 350 | 450 | 550 | 650 | 750 | 850 | 950 | 1050 | 1150 | 1250 | 1350 | 1450 | 1550 | 1650 | 1750 | 1850 | 1950 | 2050 | 2150 | 2250 | 2350 | 2450 | 2550 | 2650 | 2750 | 2850 | 2950 | 3050 | 3150 | 3250 | 3350 | 3450 | 3550 | 3650 | 3750 | 3850 | | |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-----|----|
| L | 610 | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3110 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | |
| E | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 | 1120 | 1170 | 1220 | 1270 | 1320 | 1370 | 1420 | 1470 | 1520 | 1570 | 1620 | 1670 | 1720 | 1770 | 1820 | 1870 | 1920 | 1970 | 2020 | 2070 | | |
| Weight (kg) | 14.9 | 16.6 | 18.3 | 20.0 | 21.7 | 23.5 | 25.2 | 26.9 | 28.6 | 30.3 | 32.0 | 33.7 | 35.4 | 37.1 | 38.8 | 40.5 | 42.2 | 43.9 | 45.6 | 47.3 | 49.0 | 50.7 | 52.4 | 54.1 | 55.8 | 57.5 | 59.2 | 60.9 | 62.6 | 64.3 | 66.0 | 67.7 | 69.4 | 71.1 | 72.8 | 74.5 | 76.2 | 77.9 | | |

MF30/MF30D

Can be used for wall-mount



Ordering method

Single carriage model

MF30

| Model | Cable carrier entry location | Optional cable carrier for users ^{Note 2} | Origin position change | Grease type | Stroke | Cable length |
|---|--|---|--|---------------------------------|---------------------------|--|
| MF30: Incremental MF30A: Semi-absolute ^{Note 1} | RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left | No entry: None S: S type M: M type L: L type | No entry: L side (Standard) Z: R side No entry: R side (Standard) Z: L side | No entry: Standard GC: Clean | 100 to 4000 (100mm pitch) | 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} |

TSP 220 R

| Positioner | Driver: Power-supply voltage / Power capacity | Regenerative unit | LCD monitor | I/O selection |
|------------|---|-------------------|-------------------------------|---|
| TS-P | 220: 200V/400 to 600W | R: With RGT | No entry: None L: With LCD | NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 5} |

SR1-P 20 R

| Controller | Driver: Power capacity | Usable for CE | Regenerative unit | I/O selection |
|------------|------------------------|-------------------------------------|-------------------|---|
| | 20: 400 to 600W | No entry: Standard E: CE marking | R: With RGT | N: NPN P: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PB: PROFIBUS |

RDV-P 2 20 RBR1

| Driver | Power-supply voltage | Driver: Power capacity | Regenerative unit |
|--------|----------------------|------------------------|-------------------|
| | 2: AC200V | 20: 400W or less | |

- Note 1. For the details of the semi-absolute model, please refer to P.67. RDV-P has an incremental model only.
- Note 2. For models with a stroke of 2100 or longer (2050 or longer for double carriage models), only the optional L type cable carriers can be used.
- Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.732 for details on robot cable.
- Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221HP, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 5. These controllers can be mounted on DIN rails. See P.634 for details.
- Note 6. Select this selection when using the gateway function. For details, see P.96.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.742.

Double carriage model

MF30D

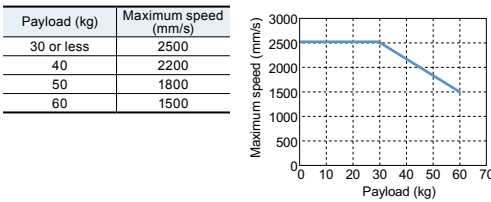
| Model | Installing direction | Optional cable carrier for users ^{Note 2} | Grease type | Stroke | Cable length | Controller |
|---|--|---|---------------------------------|---------------------------|--|--|
| MF30D: Incremental MF30AD: Semi-absolute ^{Note 1} | H: Horizontal installation W: Wall mount installation | No entry: None S: S type M: M type L: L type | No entry: Standard GC: Clean | 150 to 3750 (100mm pitch) | 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4} | RCX320 RCX221HP SR1-P (2 units) TS-P (2 units) RDV-P (2 units) |

Note. Specify various controller setting items.

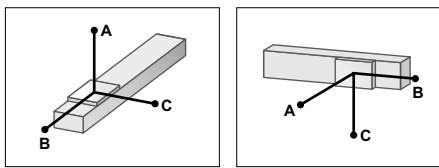
Specifications

| Model | MF30 | MF30D |
|---|---|---------------------------|
| Driving method | Steel cored linear motor with falt magnet | |
| Repeatability (µm) | +/-5 | |
| Scale (µm) | Magnetic type: resolution of 1 | |
| Maximum speed ^{Note 2} (mm/sec) | 2500 | |
| Rated thrust (N) | 125 | |
| Maximum payload ^{Note 1} (kg) | 60 | |
| Stroke (mm) | 100 to 4000 (100mm pitch) | 150 to 3750 (100mm pitch) |
| Linear guide | 4 rows of circular arc grooves x 2 rail | |
| Maximum cross-section outside dimensions (mm) | W150 x H80 (except the cable carrier section) | |
| Total length (mm) | Stroke+310 | Stroke+560 |
| Cable length (m) | Standard: 3.5 / Option: 5,10 | |

- Note. A vertical model (with brake) is not available with the PHASER series.
- Note. The basic specifications of semi-absolute model are the same as those of the incremental model.
- Note 1. Payload per carrier. When the payload exceeds 30kg, please consult our sales office or sales representative.
- Note 2. Table of maximum speed



Allowable overhang



| | Horizontal installation (Unit: mm) | | | Wall installation (Unit: mm) | | |
|------|------------------------------------|------|------|------------------------------|------|------|
| | A | B | C | A | B | C |
| 10kg | 3364 | 2485 | 1284 | 1290 | 1320 | 2730 |
| 20kg | 2298 | 1265 | 694 | 650 | 610 | 1750 |
| 30kg | 2060 | 859 | 507 | 430 | 360 | 1460 |
| 40kg | 1570 | 600 | 310 | 205 | 230 | 610 |
| 50kg | 1265 | 400 | 180 | 145 | 175 | 470 |
| 60kg | 1070 | 350 | 135 | 105 | 140 | 380 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

| MY | MP | MR |
|-----|-----|-----|
| 373 | 373 | 328 |

(Unit: N-m)

Controller

| Controller | Operating method |
|----------------------------------|--|
| SR1-P20-R | Programming / I/O point trace / Remote command / Operation using RS-232C communication |
| RCX320-R RCX221HP-R RCX340 | I/O point trace / Remote command |
| TS-P220-R | Pulse train control |
| RDV-P220-RBR1 | |

Cable carrier entry location

RH Horizontal, right **LH Horizontal, left**

RW Wall mounted, right **LW Wall mounted, left**

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Optional cable carrier for users

S type **M type** **L type**

Cable and air tube guide

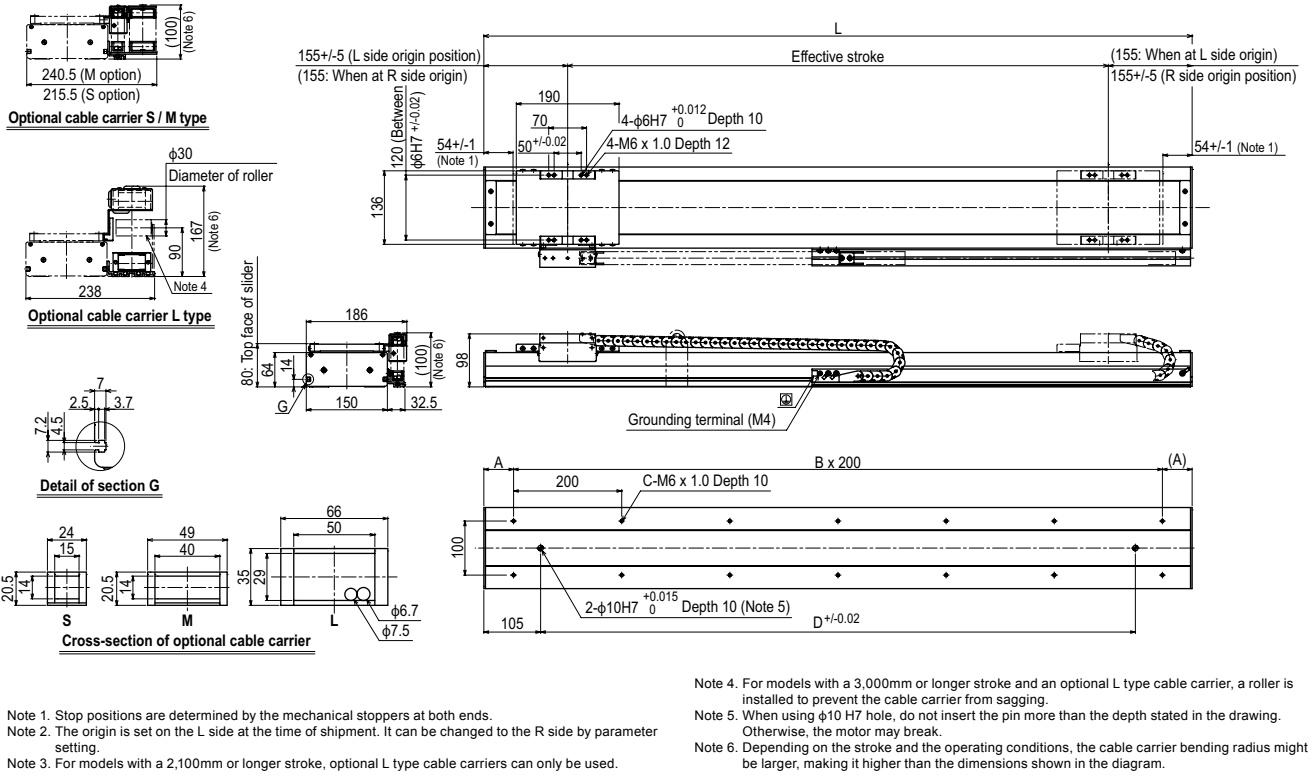
S: φ8 flexible cable x 1, φ4 air tube x 1
M: φ8 flexible cable x 2, φ6 air tube x 2
L: φ8 flexible cable x 2, φ6 air tube x 3

Space for optional cable for users

Controller

SR1-P ▶ 652 **RCX320 ▶ 660** **RCX221 ▶ 670** **TS-P ▶ 626** **RDV-P ▶ 640**

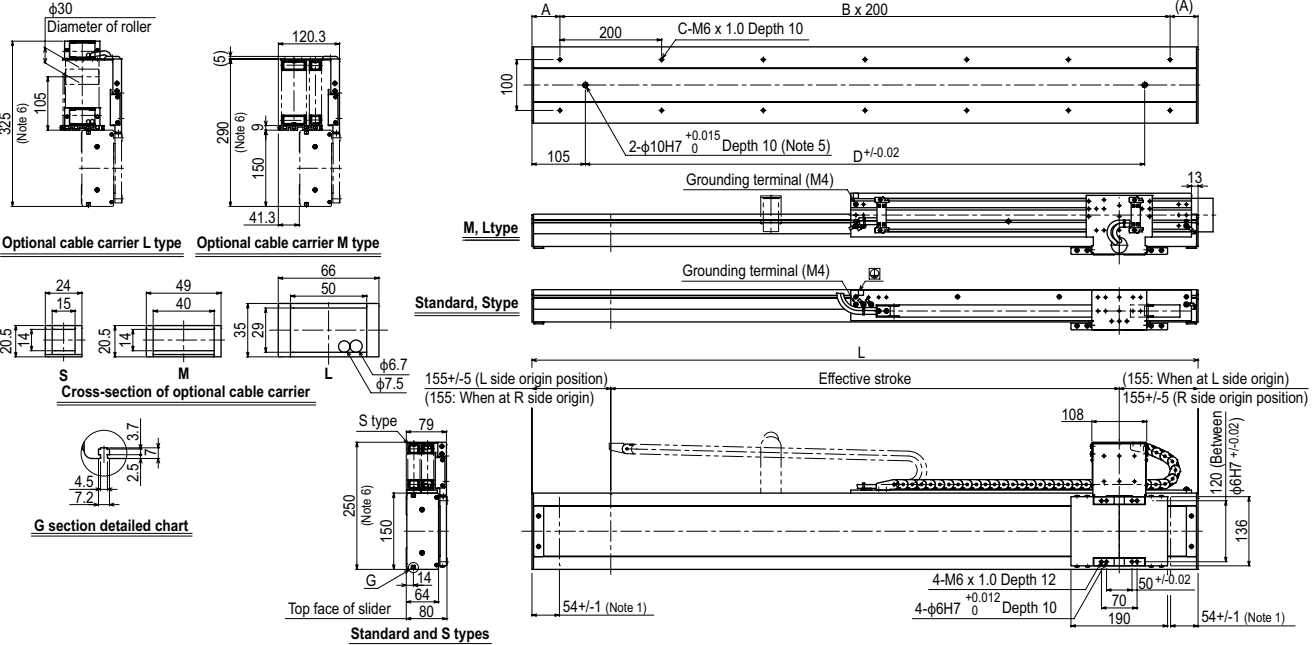
MF30 single carriage horizontal mount model **RH**



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | | |
|------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|----|
| L | 410 | 510 | 610 | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3100 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 1 | 2 | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 4 | 6 | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | |
| Weight (kg) | 9.0 | 10.7 | 12.3 | 13.9 | 15.6 | 17.2 | 18.8 | 20.4 | 22.2 | 23.7 | 25.2 | 26.7 | 28.3 | 29.8 | 31.4 | 33.1 | 34.7 | 36.4 | 38.1 | 40.0 | 41.7 | 43.4 | 45.1 | 46.8 | 48.5 | 50.2 | 52.0 | 53.7 | 55.5 | 57.3 | 59.1 | 60.9 | 62.7 | 64.5 | 66.4 | 68.2 | 70.0 | 71.9 | 73.7 | 75.5 | 77.3 | |

MF30 single carriage wall mount model **RW**



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.
 Note 3. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | | |
|------------------|-----|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|----|
| L | 410 | 510 | 610 | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3100 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 1 | 2 | 2 | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 4 | 6 | 6 | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | |
| Weight (kg) | 9.0 | 10.7 | 12.3 | 13.9 | 15.6 | 17.2 | 18.8 | 20.4 | 22.2 | 23.7 | 25.2 | 26.7 | 28.3 | 29.8 | 31.4 | 33.1 | 34.7 | 36.4 | 38.1 | 40.0 | 41.7 | 43.4 | 45.1 | 46.8 | 48.5 | 50.2 | 52.0 | 53.7 | 55.5 | 57.3 | 59.1 | 60.9 | 62.7 | 64.5 | 66.4 | 68.2 | 70.0 | 71.9 | 73.7 | 75.5 | 77.3 | |

MF30D double carriage horizontal mount model **H**

Optional cable carrier S / M type
240.5 (M option)
215.5 (S option)
100 (Note 6)

Optional cable carrier L type
φ30 Diameter of roller
167 (Note 6)
90 (Note 4)
238

Detail of section G
7.2, 4.5, 2.5, 3.7

Cross-section of optional cable carrier
S, M, L, φ6.7, φ7.5

Effective stroke L
155+/-5 (Note 1)
190
50 +/-0.02
70
4-φ6H7 +0.012 Depth 10
4-M6 x 1.0 Depth 12
4-φ6H7 +0.012 Depth 10
4-M6 x 1.0 Depth 12
155+/-5 (Note 1)
190
70
50 +/-0.02
54+/-1 (Note 2)
120 (Between φ6H7 +0.02)
136
80, Top face of slider
186
64, 14, 150, 32.5, 98
Grounding terminal (M4)

Standard and S types
A, B x 200, C-M6 x 1.0 Depth 10, 100, 105, 2-φ10H7 +0.015 Depth 10 (Note 5), D +/-0.02

Standard and S types
S type 79
250 (Note 6)
150
G, 14, 64, 80
Top face of slider
54+/-1 (Note 2)
120 (Between φ6H7 +0.02)
136
50 +/-0.02
70
4-φ6H7 +0.012 Depth 10
4-M6 x 1.0 Depth 12
4-M6 x 1.0 Depth 12
4-φ6H7 +0.012 Depth 10
190
120 (Between φ6H7 +0.02)
136

Notes:
Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 150 | 250 | 350 | 450 | 550 | 650 | 750 | 850 | 950 | 1050 | 1150 | 1250 | 1350 | 1450 | 1550 | 1650 | 1750 | 1850 | 1950 | 2050 | 2150 | 2250 | 2350 | 2450 | 2550 | 2650 | 2750 | 2850 | 2950 | 3050 | 3150 | 3250 | 3350 | 3450 | 3550 | 3650 | 3750 | | |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-----|
| L | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3110 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | 4200 | |
| Weight (kg) | 17.6 | 19.3 | 21.0 | 22.2 | 24.2 | 25.2 | 27.7 | 29.9 | 29.6 | 31.3 | 33.3 | 33.4 | 37.3 | 53.8 | 23.9 | 9.41 | 6.43 | 3.45 | 0.46 | 7.48 | 4.50 | 2.51 | 9.53 | 6.55 | 3.57 | 0.58 | 7.60 | 4.62 | 1.63 | 9.65 | 6.67 | 3.69 | 0.70 | 7.72 | 4.74 | 1.75 | 8.77 | 5.79 | 3.0 |

MF30D double carriage wall mount model **W**

Optional cable carrier L type
φ30 Diameter of roller
325 (Note 6)
105
290 (Note 6)
180
41.3

Optional cable carrier M type
120.3
66
50
35
29
φ6.7
φ7.5

Detail of section G
4.5, 2.5, 3.7, 7.2

Cross-section of optional cable carrier
S, M, L, φ6.7, φ7.5

Standard and S types
A, B x 200, C-M6 x 1.0 Depth 10, 100, 105, 2-φ10H7 +0.015 Depth 10 (Note 5), D +/-0.02

Standard and S types
S type 79
250 (Note 6)
150
G, 14, 64, 80
Top face of slider
54+/-1 (Note 2)
120 (Between φ6H7 +0.02)
136
50 +/-0.02
70
4-φ6H7 +0.012 Depth 10
4-M6 x 1.0 Depth 12
4-M6 x 1.0 Depth 12
4-φ6H7 +0.012 Depth 10
190
120 (Between φ6H7 +0.02)
136

Notes:
Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 150 | 250 | 350 | 450 | 550 | 650 | 750 | 850 | 950 | 1050 | 1150 | 1250 | 1350 | 1450 | 1550 | 1650 | 1750 | 1850 | 1950 | 2050 | 2150 | 2250 | 2350 | 2450 | 2550 | 2650 | 2750 | 2850 | 2950 | 3050 | 3150 | 3250 | 3350 | 3450 | 3550 | 3650 | 3750 | | |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|-----|
| L | 710 | 810 | 910 | 1010 | 1110 | 1210 | 1310 | 1410 | 1510 | 1610 | 1710 | 1810 | 1910 | 2010 | 2110 | 2210 | 2310 | 2410 | 2510 | 2610 | 2710 | 2810 | 2910 | 3010 | 3110 | 3210 | 3310 | 3410 | 3510 | 3610 | 3710 | 3810 | 3910 | 4010 | 4110 | 4210 | 4310 | | |
| A | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 | 105 | 55 |
| B | 3 | 3 | 4 | 4 | 5 | 5 | 6 | 6 | 7 | 7 | 8 | 8 | 9 | 9 | 10 | 10 | 11 | 11 | 12 | 12 | 13 | 13 | 14 | 14 | 15 | 15 | 16 | 16 | 17 | 17 | 18 | 18 | 19 | 19 | 20 | 20 | 21 | 21 | |
| C | 8 | 8 | 10 | 10 | 12 | 12 | 14 | 14 | 16 | 16 | 18 | 18 | 20 | 20 | 22 | 22 | 24 | 24 | 26 | 26 | 28 | 28 | 30 | 30 | 32 | 32 | 34 | 34 | 36 | 36 | 38 | 38 | 40 | 40 | 42 | 42 | 44 | 44 | |
| D | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | 4200 | |
| E | 220 | 270 | 320 | 370 | 420 | 470 | 520 | 570 | 620 | 670 | 720 | 770 | 820 | 870 | 920 | 970 | 1020 | 1070 | 1120 | 1170 | 1220 | 1270 | 1320 | 1370 | 1420 | 1470 | 1520 | 1570 | 1620 | 1670 | 1720 | 1770 | 1820 | 1870 | 1920 | 1970 | 2020 | | |
| Weight (kg) | 17.6 | 19.3 | 21.0 | 22.2 | 24.2 | 25.2 | 27.7 | 29.9 | 29.6 | 31.3 | 33.3 | 33.4 | 37.3 | 53.8 | 23.9 | 9.41 | 6.43 | 3.45 | 0.46 | 7.48 | 4.50 | 2.51 | 9.53 | 6.55 | 3.57 | 0.58 | 7.60 | 4.62 | 1.63 | 9.65 | 6.67 | 3.69 | 0.70 | 7.72 | 4.74 | 1.75 | 8.77 | 5.79 | 3.0 |

MF75/MF75D



Ordering method

Single carriage model

MF75

| | | | | | | | | | | |
|---|--|---|---|---|---|---|---|---|---|---|
| Model MF75: Incremental MF75A: Semi-absolute ^{Note 1} | Cable carrier entry location RH: Horizontal, right LH: Horizontal, left | Origin position change No entry: L side (Standard) Z: R side | Grease type No entry: Standard GC: Clean | Stroke 1000 to 4000 (100mm pitch) | Cable length ^{Note 2} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 3} | TSP Positioner ^{Note 4} TS-P | 220 Driver: Power-supply voltage / Power capacity 220: 200V/400 to 600W | R Regenerative unit R: With RGU-2 | LCD monitor No entry: None L: With LCD | I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 5} |
|---|--|---|---|---|---|---|---|---|---|---|

SR1-P **20** **R**

| | | | | |
|-------------------|--|---|---|---|
| Controller | Driver: Power capacity 20: 400 to 600W | Usable for CE No entry: Standard E: CE marking | Regenerative unit R: With RGU-2 | I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS |
|-------------------|--|---|---|---|

RDV-P **2** **25** **RBR2**

| | | | |
|---------------|--|---|--------------------------|
| Driver | Power-supply voltage 2: AC200V | Driver: Power capacity 25: 750W or less | Regenerative unit |
|---------------|--|---|--------------------------|

- Note 1. For the details of the semi-absolute model, please refer to P.67. RDV-P has an incremental model only.
- Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.732 for details on robot cable.
- Note 3. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221HP, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 4. These controllers can be mounted on DIN rails. See P.634 for details.
- Note 5. Select this selection when using the gateway function. For details, see P.96.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.742.

Double carriage model

MF75D - **H**

| | | | | | |
|---|---|---|--|---|---|
| Model MF75D: Incremental MF75AD: Semi-absolute ^{Note 1} | Installing direction H: Horizontal installation | Grease type No entry: Standard GC: Clean | Stroke 680 to 3680 (100mm pitch) | Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 3} | Controller RCX320 RCX221HP SR1-P (2 units) TS-P (2 units) RDV-P (2 units) |
|---|---|---|--|---|---|

Note. Specify various controller setting items.

Specifications

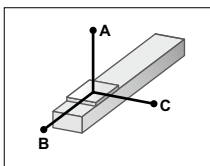
| Model | MF75 | MF75D |
|--|--|---------------------------|
| Driving method | Steel cored linear motor with falt magnet | |
| Repeatability (µm) | +/-5 | |
| Scale (µm) | Magnetic type: resolution of 1 | |
| Maximum speed ^{Note 2} (mm/sec) | 2500 | |
| Rated thrust (N) | 260 | |
| Maximum payload ^{Note 1} (kg) | 160 | |
| Stroke (mm) | 1000 to 4000 (100mm pitch) | 680 to 3680 (100mm pitch) |
| Linear guide | 4 rows of circular arc grooves x 2 rail | |
| Maximum cross-section outside dimensions (mm) | W210xH100 (except the cable carrier section) | |
| Total length (mm) | Stroke+360 | Stroke+680 |
| Cable length (m) | Standard: 3.5 / Option: 5,10 | |

Note. A vertical model (with brake) is not available with the PHASER series.
Note. The basic specifications of semi-absolute model are the same as those of the incremental model.
Note 1. Payload per carrier. When the payload exceeds 75kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed

| Payload (kg) | Maximum speed (mm/s) |
|--------------|----------------------|
| 75 or less | 2500 |
| 90 | 2310 |
| 100 | 2200 |
| 110 | 2090 |
| 120 | 2000 |
| 130 | 1920 |
| 140 | 1840 |
| 150 | 1770 |
| 160 | 1700 |

Allowable overhang

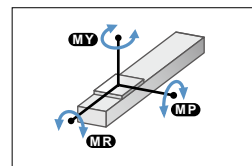


Horizontal installation (Unit: mm)

| | A | B | C |
|-------|------|------|------|
| 20kg | 3397 | 2841 | 1840 |
| 40kg | 2795 | 1389 | 964 |
| 60kg | 2200 | 530 | 450 |
| 80kg | 1800 | 175 | 150 |
| 100kg | 1500 | 130 | 110 |
| 120kg | 1250 | 100 | 80 |
| 140kg | 1100 | 80 | 65 |
| 160kg | 950 | 60 | 50 |

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



| (Unit: N-m) | | |
|-------------|-----|-----|
| MY | MP | MR |
| 830 | 831 | 730 |

Controller

| Controller | Operating method |
|---------------|----------------------------------|
| SR1-P20-R | Programming / I/O point trace / |
| RCX320-R | Remote command / |
| RCX221HP-R | Operation using RS-232C |
| RCX340 | communication |
| TS-P220-R | I/O point trace / Remote command |
| RDV-P225-RBR2 | Pulse train control |

Cable carrier entry location

RH Horizontal, right **LH Horizontal, left**

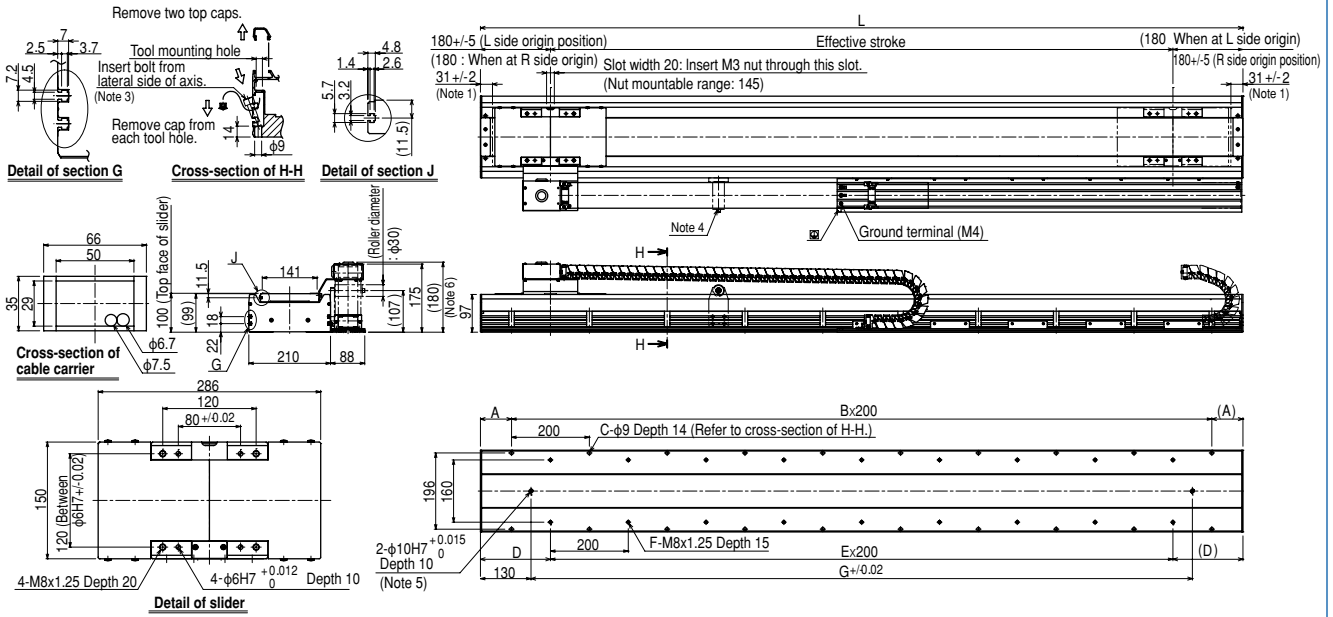
Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Cable carrier

Cable and air tube guide φ8 flexible cable x 2, φ6 air tube x 3

Space for optional cable for users

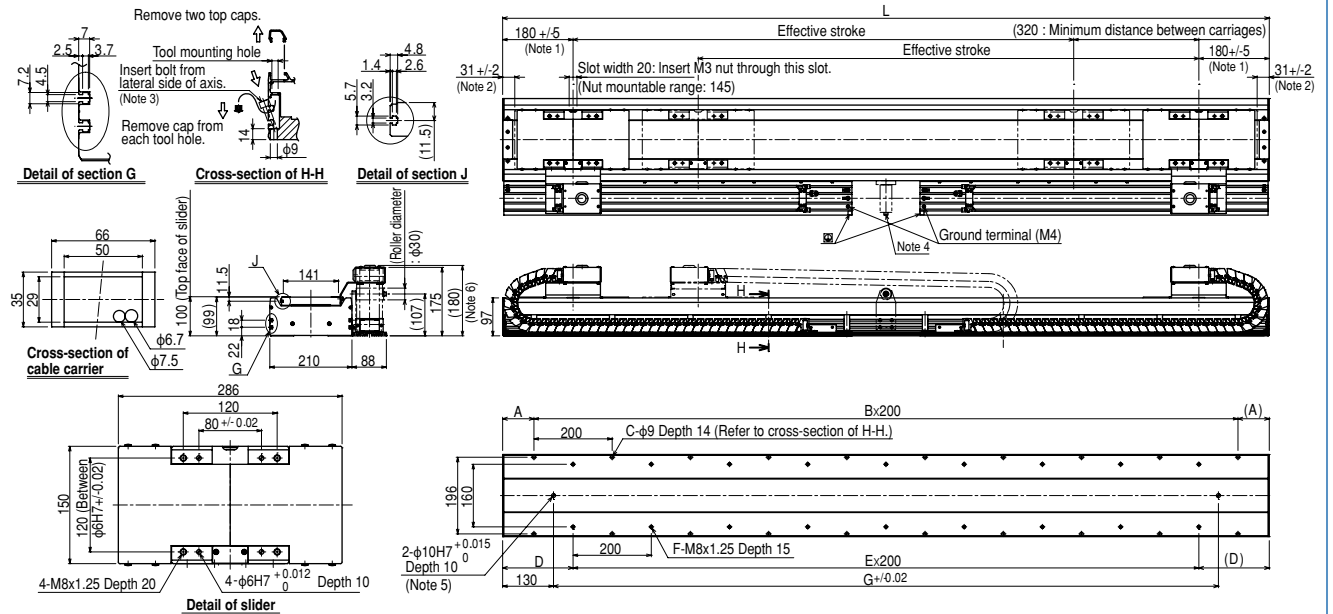
MF75 single carriage horizontal mount model **RH**



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side (as shown above) at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The length under head of M8 hex socket head bolts for installing the robot body must not be longer than 30mm.
 Note 4. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 1000 | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 | 2360 | 2460 | 2560 | 2660 | 2760 | 2860 | 2960 | 3060 | 3160 | 3260 | 3360 | 3460 | 3560 | 3660 | 3760 | 3860 | 3960 | 4060 | 4160 | 4260 | 4360 |
| A | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 |
| B | 5 | 5 | 7 | 7 | 7 | 7 | 9 | 9 | 9 | 9 | 11 | 11 | 11 | 11 | 13 | 13 | 13 | 13 | 13 | 15 | 15 | 15 | 17 | 17 | 17 | 17 | 19 | 19 | 19 | 19 | 21 |
| C | 12 | 12 | 16 | 16 | 16 | 16 | 20 | 20 | 20 | 20 | 24 | 24 | 24 | 24 | 28 | 28 | 28 | 28 | 28 | 32 | 32 | 32 | 32 | 36 | 36 | 36 | 36 | 40 | 40 | 40 | 44 |
| D | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 |
| E | 6 | 6 | 6 | 6 | 8 | 8 | 8 | 8 | 10 | 10 | 10 | 10 | 12 | 12 | 12 | 12 | 14 | 14 | 14 | 14 | 16 | 16 | 16 | 16 | 18 | 18 | 18 | 18 | 20 | 20 | 20 |
| F | 14 | 14 | 14 | 14 | 18 | 18 | 18 | 18 | 22 | 22 | 22 | 22 | 26 | 26 | 26 | 26 | 30 | 30 | 30 | 30 | 34 | 34 | 34 | 34 | 38 | 38 | 38 | 38 | 42 | 42 | 42 |
| G | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 |
| Weight (kg) | 46 | 49 | 51 | 54 | 56 | 59 | 61 | 64 | 66 | 69 | 71 | 74 | 76 | 79 | 81 | 84 | 86 | 89 | 91 | 94 | 96 | 99 | 101 | 104 | 106 | 109 | 111 | 114 | 116 | 119 | 121 |

MF75D double carriage mount model **H**



Note 1. Position of table carriage when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. The length under head of M8 hex socket head bolts for installing the robot body must not be longer than 30mm.
 Note 4. For models with a 3,080mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

| Effective stroke | 680 | 780 | 880 | 980 | 1080 | 1180 | 1280 | 1380 | 1480 | 1580 | 1680 | 1780 | 1880 | 1980 | 2080 | 2180 | 2280 | 2380 | 2480 | 2580 | 2680 | 2780 | 2880 | 2980 | 3080 | 3180 | 3280 | 3380 | 3480 | 3580 | 3680 | 3780 | 3880 | 3980 | 4080 | 4180 |
|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| L | 1360 | 1460 | 1560 | 1660 | 1760 | 1860 | 1960 | 2060 | 2160 | 2260 | 2360 | 2460 | 2560 | 2660 | 2760 | 2860 | 2960 | 3060 | 3160 | 3260 | 3360 | 3460 | 3560 | 3660 | 3760 | 3860 | 3960 | 4060 | 4160 | 4260 | 4360 | | | | | |
| A | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | |
| B | 5 | 5 | 7 | 7 | 7 | 7 | 9 | 9 | 9 | 9 | 11 | 11 | 11 | 11 | 13 | 13 | 13 | 13 | 13 | 15 | 15 | 15 | 17 | 17 | 17 | 17 | 19 | 19 | 19 | 19 | 21 | | | | | |
| C | 12 | 12 | 16 | 16 | 16 | 16 | 20 | 20 | 20 | 20 | 24 | 24 | 24 | 24 | 28 | 28 | 28 | 28 | 28 | 32 | 32 | 32 | 32 | 36 | 36 | 36 | 36 | 40 | 40 | 40 | 44 | | | | | |
| D | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | 230 | 80 | 130 | 180 | |
| E | 6 | 6 | 6 | 6 | 8 | 8 | 8 | 8 | 10 | 10 | 10 | 10 | 12 | 12 | 12 | 12 | 14 | 14 | 14 | 14 | 16 | 16 | 16 | 16 | 18 | 18 | 18 | 18 | 20 | 20 | 20 | 20 | | | | |
| F | 14 | 14 | 14 | 14 | 18 | 18 | 18 | 18 | 22 | 22 | 22 | 22 | 26 | 26 | 26 | 26 | 30 | 30 | 30 | 30 | 34 | 34 | 34 | 34 | 38 | 38 | 38 | 38 | 42 | 42 | 42 | 42 | | | | |
| G | 1100 | 1200 | 1300 | 1400 | 1500 | 1600 | 1700 | 1800 | 1900 | 2000 | 2100 | 2200 | 2300 | 2400 | 2500 | 2600 | 2700 | 2800 | 2900 | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | 4000 | 4100 | | | | | |
| Weight (kg) | 57 | 60 | 62 | 65 | 67 | 70 | 73 | 75 | 78 | 81 | 83 | 86 | 88 | 91 | 94 | 96 | 99 | 101 | 104 | 107 | 109 | 112 | 114 | 117 | 120 | 122 | 125 | 127 | 130 | 133 | 135 | | | | | |

MEMO

Articulated
robots
YA

Linear conveyor
modules
LCM

Single-axis robots
CX

Motorless single
axis actuator
Robonity

Compact
single-axis robots
TRANSEVO

Single-axis robots
FLIP-X

Linear motor
single-axis robots
PHASER

Cartesian
robots
XY-X

SCARA
robots
YK-X

Pick & place
robots
YP-X

CLEAN

CONTROLLER

INFORMATION