

# YK600XC

Clean type: Medium type



- Arm length 600mm
- Maximum payload 10kg

## Ordering method

|                |                          |                                |   |                        |                        |                        |                        |                        |                        |                         |
|----------------|--------------------------|--------------------------------|---|------------------------|------------------------|------------------------|------------------------|------------------------|------------------------|-------------------------|
| <b>YK600XC</b> |                          |                                | <b>RCX340-4</b>                                 |                        |                        |                        |                        |                        |                        |                         |
| <b>Model</b>   | <b>Z axis stroke</b>     | <b>Cable length</b>            | <b>Controller / Number of controllable axes</b> | <b>Safety standard</b> | <b>Option A (OP.A)</b> | <b>Option B (OP.B)</b> | <b>Option C (OP.C)</b> | <b>Option D (OP.D)</b> | <b>Option E (OP.E)</b> | <b>Absolute battery</b> |
|                | 200: 200mm<br>300: 300mm | 3L: 3.5m<br>5L: 5m<br>10L: 10m |   |                        |                        |                        |                        |                        |                        |                         |

Specify various controller setting items. RCX340 ▶ **P.678**

## Basic specifications

| Axis specifications  | Arm length (mm)    | X axis  | Y axis | Z axis    | R axis   |
|--|--------------------|---|--------|-----------|----------|
|  |                    | 350   | 250    | 200   300 | -        |
|  | Rotation angle (°) | +/-120  | +/-145 | -         | +/-180   |
| <b>AC servo motor output (W)</b>   |                    | 400   | 200    | 200       | 100      |
| <b>Repeatability<sup>Note 1</sup> (XYZ: mm) (R: °)</b>                       |                    | +/-0.02   |        | +/-0.01   | +/-0.005 |
| <b>Maximum speed (XYZ: m/sec) (R: °/sec)</b>                                 |                    | 5.6   |        | 1.7       | 876      |
| <b>Maximum payload (kg)</b>  |                    | 10  |        |           |          |
| <b>Standard cycle time: with 2kg payload (sec)</b>                           |                    | 0.56  |        |           |          |
| <b>R-axis tolerable moment of inertia<sup>Note 2</sup> (kgm<sup>2</sup>)</b> |                    | 0.12  |        |           |          |
| <b>User wiring (sq x wires)</b>  |                    | 0.2 x 20  |        |           |          |
| <b>User tubing (Outer diameter)</b>  |                    | φ6 x 3  |        |           |          |
| <b>Travel limit</b>  |                    | 1.Soft limit, 2.Mechanical stopper (X, Y, Z axes) |        |           |          |
| <b>Robot cable length (m)</b>  |                    | Standard: 3.5 Option: 5, 10                       |        |           |          |
| <b>Weight (kg)</b>   |                    | 33  |        |           |          |
| <b>Degree of cleanliness</b>   |                    | CLASS 10 <sup>Note 3</sup>                        |        |           |          |
| <b>Intake air (Nl/min)</b>   |                    | 60 <sup>Note 4</sup>                              |        |           |          |

Note 1. This is the value at a constant ambient temperature. (X,Y axes)  
 Note 2. The acceleration coefficient is set automatically in accordance with the tip weight and R-axis moment of inertia settings.  
 Note 3. Per 1cf (0.1μm base), when suction blower is used.  
 Note 4. The necessary intake amount varies depending on the use conditions and environment.

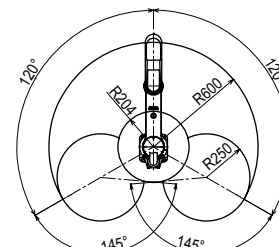
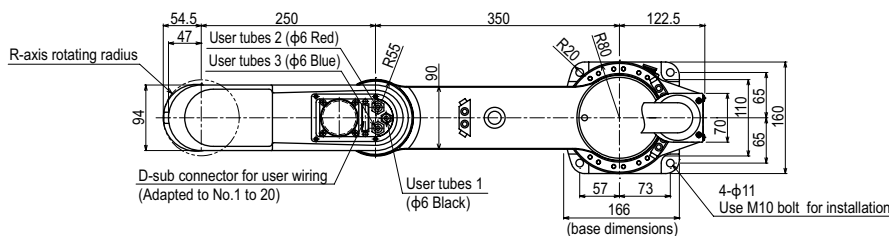
## Controller

| Controller | Power capacity (VA) | Operation method   |
|------------|---------------------|--|
| RCX340     | 1500                | Programming / I/O point trace / Remote command / Operation using RS-232C communication |

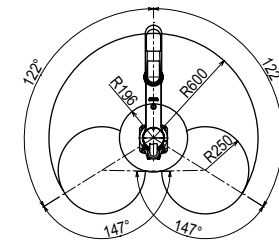
Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)  
 See our robot manuals (installation manuals) for detailed information.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:  
<https://global.yamaha-motor.com/business/robot/>

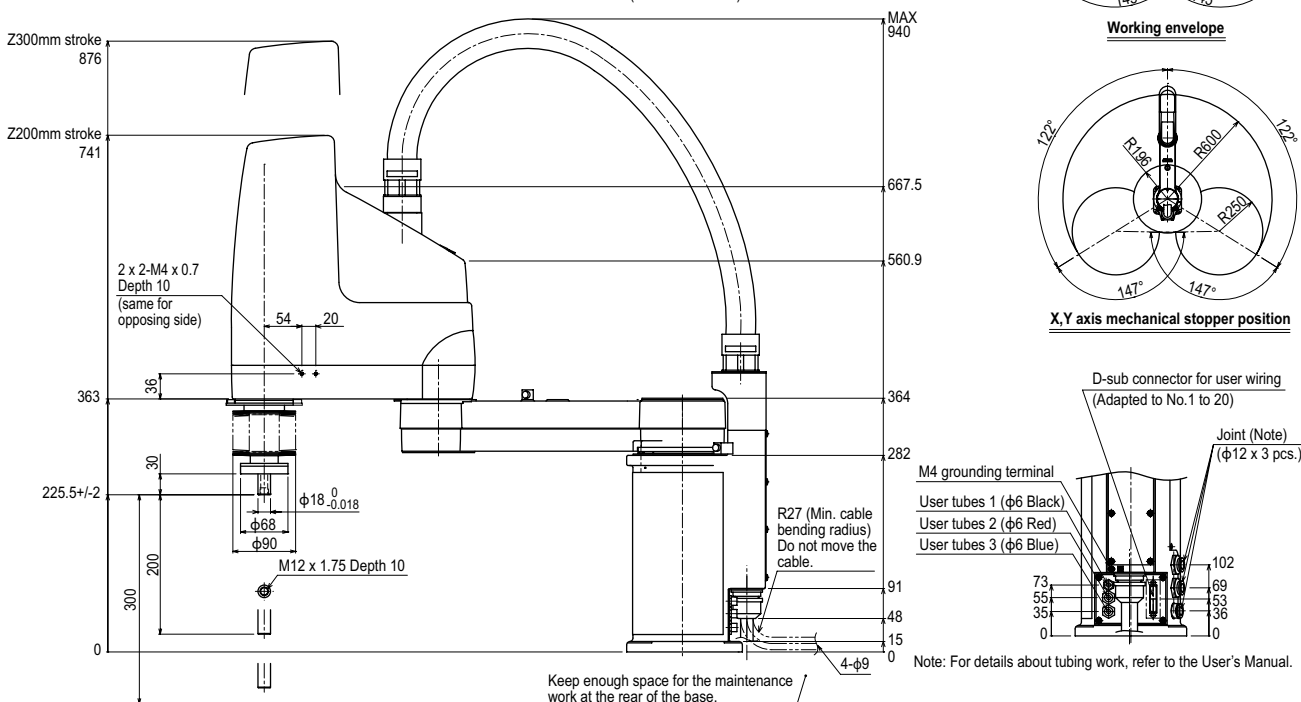
## YK600XC



Working envelope



X,Y axis mechanical stopper position



Keep enough space for the maintenance work at the rear of the base.

Note: For details about tubing work, refer to the User's Manual.