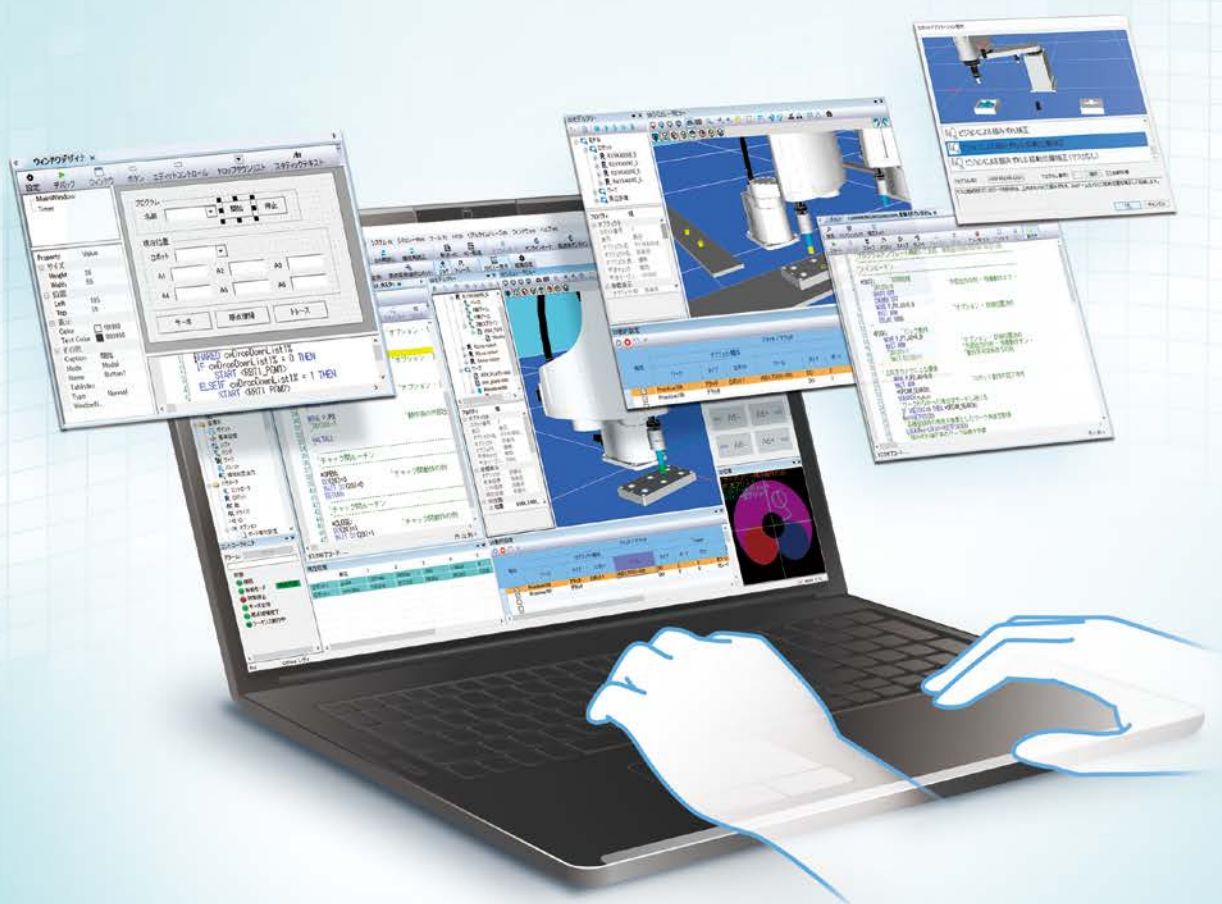


**NEW**

3D simulator function  
Program template function  
Custom window creation function



RCX 3 Series CONTROLLER PROGRAMMING SOFTWARE

# RCX-Studio 2020

Robot operation from start up to maintenance

# New features to greatly reduce startup time

Programming software for RCX 3 series controllers

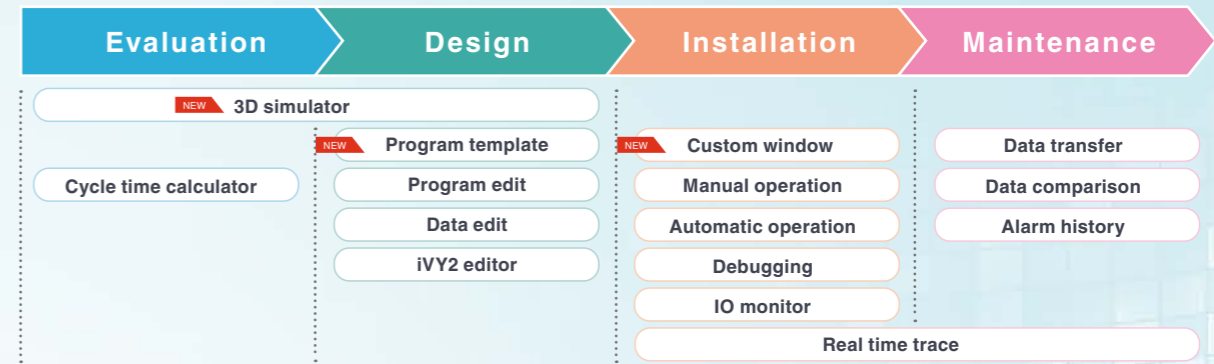
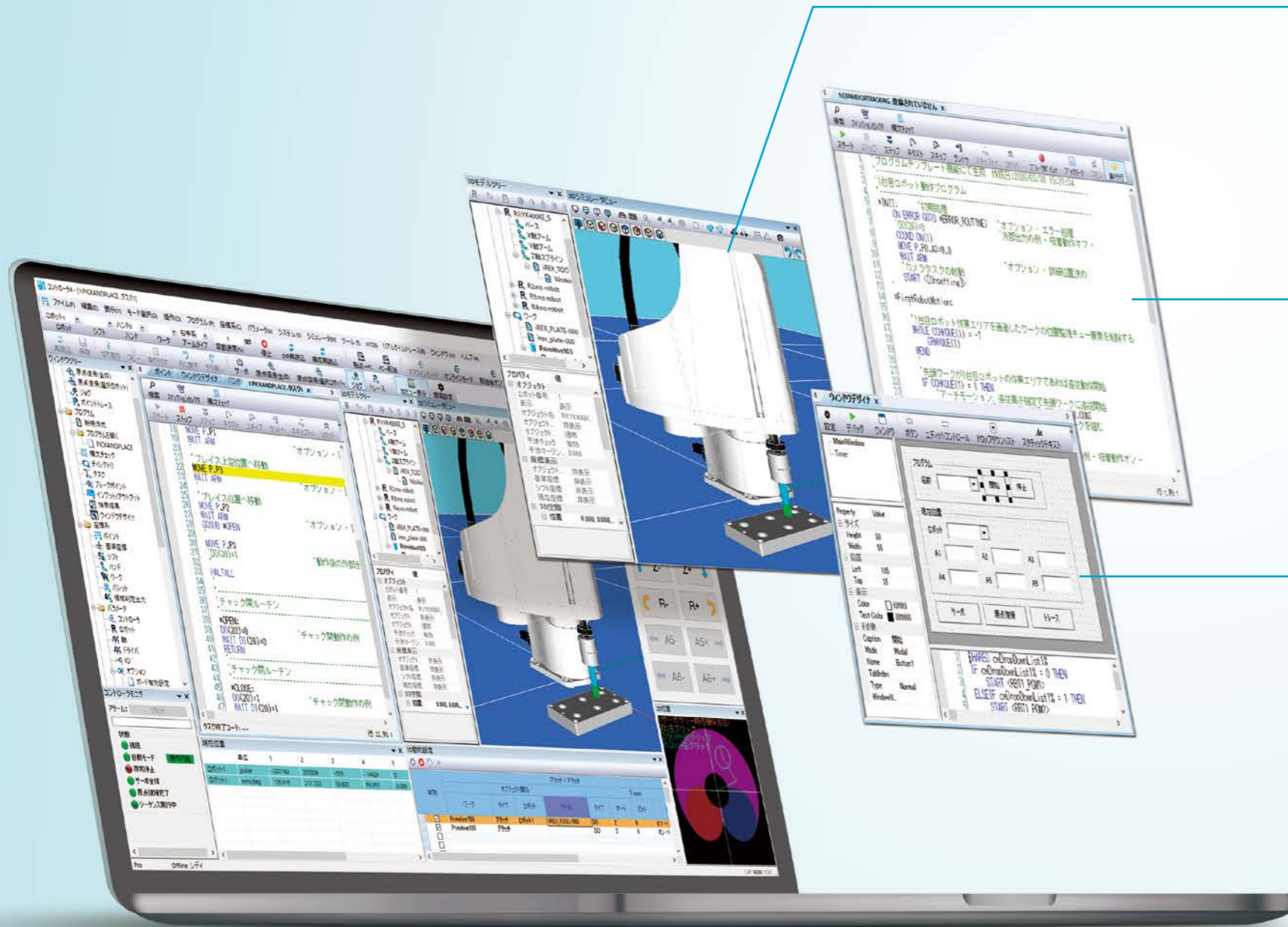
# RCX-Studio 2020



Improves production startup time

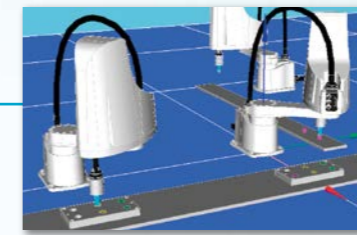
Start programming before robot delivery

New functions such as 3D simulator function and program template (program template automatic creation function) are added for ease of user operation.



## NEW 3D simulator

See 04P.



**Layout can be verified beforehand without connecting robot.**

Robots and peripheral devices are displayed in 3D, and the robot operation is simulated on PC.

- ▶ Robot layout, teaching, and debugging can be performed.
- ▶ Physical interference between the robot and peripheral device can be checked before operation is started.

## NEW Program template (Program template automatic creation function)

See 06P.



**Program creation time can be shortened greatly.**

Program templates for 10 types of applications are incorporated. Just following the steps to perform the operation creates a program template automatically.

## NEW Custom window creation

See 08P.

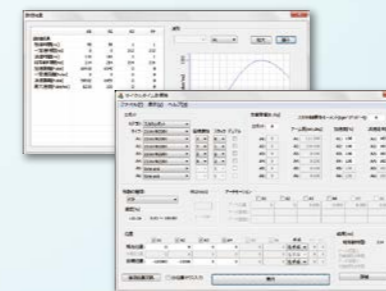


**Operation screens suitable for the customer's equipment can be created.**

GUIs for operators that are displayed on the panel computer can be created.

## Other existing functions

See 09P.



All useful features from RCX-Studio Pro are succeeded to help supporting from startup to maintenance.

- Cycle time calculator
- Real time trace
- Data comparison

# Layout verification, teaching, and debugging without connecting robots

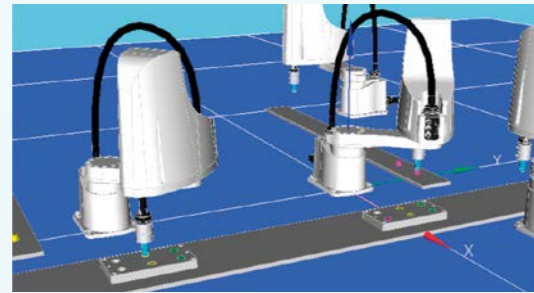
## NEW 3D simulator

Robots and peripheral devices are displayed in 3D, and the robot operation is simulated.



### 3D CAD Data imported

- Multiple robots are supported (up to 4 robots).  
\* Only SCARA robot is supported. Cartesian robot and single-axis robot are not supported.

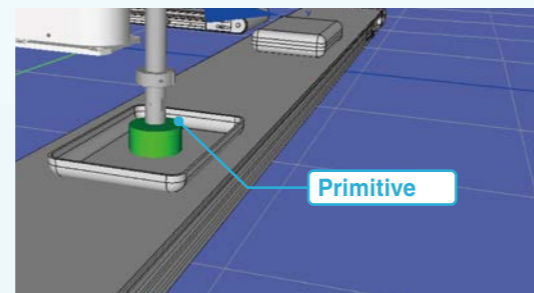


Importable data: STL, Wavefront OBJ, VRML2.0, STEP\*

\* Only Pro version is supported. Supported format: AP204, AP214

### Peripheral devices are displayed using primitives.

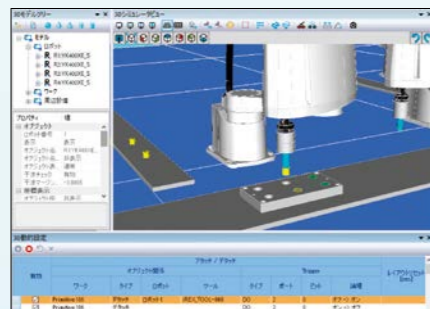
- Peripheral devices and workpieces can be displayed using simple shapes (primitives).



Primitive

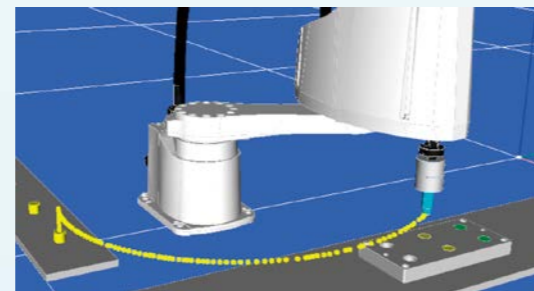
### Teaching virtual robot on screen

- Teaching of the current position can be performed by moving virtual robots using the jog or mouse operation.



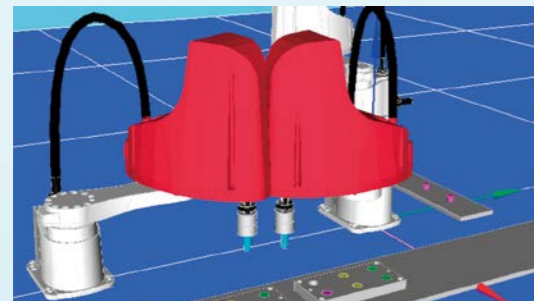
### Operation area is verified by tracing the movement of end-of-arm effector and parts

- Visually tracing robot move
- Movement of workpiece and end effector can be displayed.



### Interference with the production units is checked to avoid collision with other devices.

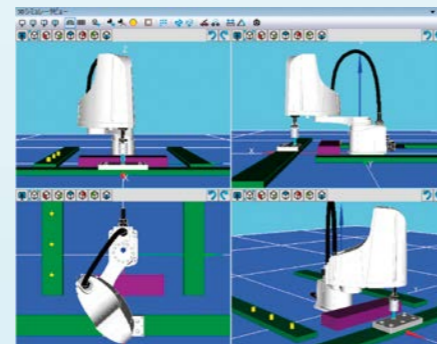
- Interference between the robot and peripheral device is checked.



\* Interference check is performed at the screen drawing timing. Therefore, the interference may not be detected depending on the execution environment and operation status of the software. To perform the accurate check, it is recommended to decrease the operation speed of the robot and perform the check several times.

### Multi-angle View (Screen division function)

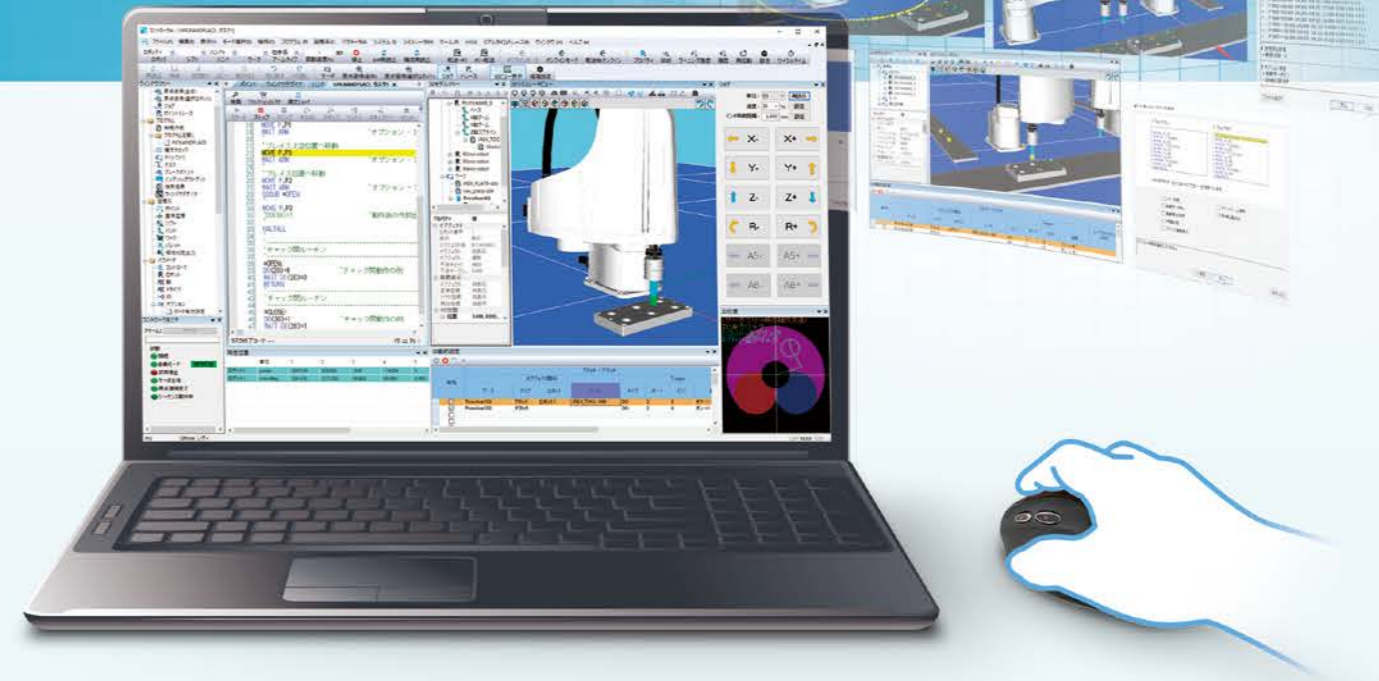
- Layout can be checked from multiple viewpoints at the same time.



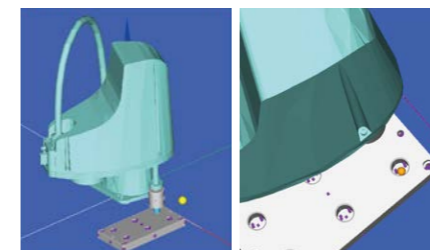
### Video capture \*

\* Planned to support this function in July, 2020.

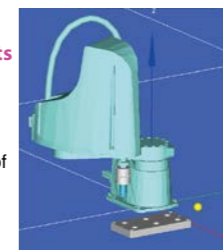
- The simulation results are output as a video.



### STEP data file can be imported.



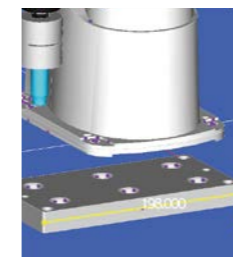
**Pro**  
Characteristic points with STEP file data are displayed.  
For the STEP data, characteristic points of the 3D CAD data are displayed. Clicking the characteristic point moves the robot.



**Basic**  
For data other than the STEP data, characteristic points of the 3D CAD data are not displayed.

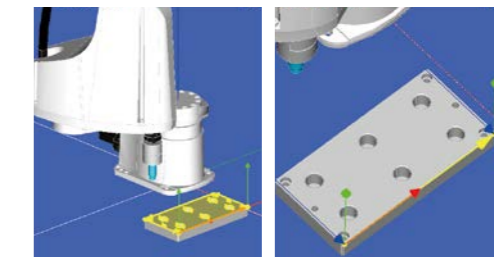
### Measurement of distance and angle

With STEP file data the distance and angle can be measured using the characteristic points on the edge.



### Creation of edge point data

With STEP file data the characteristic points on the edge can be converted into the point data.



# Easy programming with wizards.

NEW

## Program template

Program templates of ten types of applications



Just following the steps to perform the operation creates a program automatically.

**Robot application selection**  
Application is selected from the dialog box.

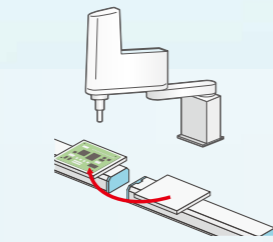
Setting with wizards

Option function selection

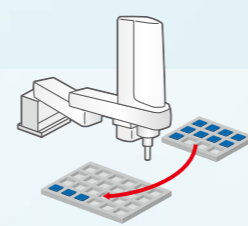
Program template is created automatically.

### Supported applications

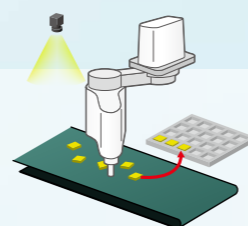
- Pick & place
- Palletizing
- Dispensing work
- Execution program switching
- Conveyor tracking
- Pallet picking using vision
- Dispensing with vision
- Gripping deviation correction using vision
- Parts orientation adjustment on the fly with vision
- Parts orientation adjustment on the fly with vision (without master)



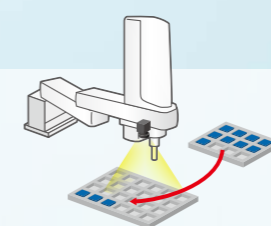
● Pick & place



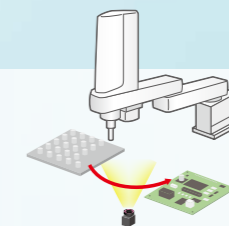
● Palletizing



● Conveyor tracking



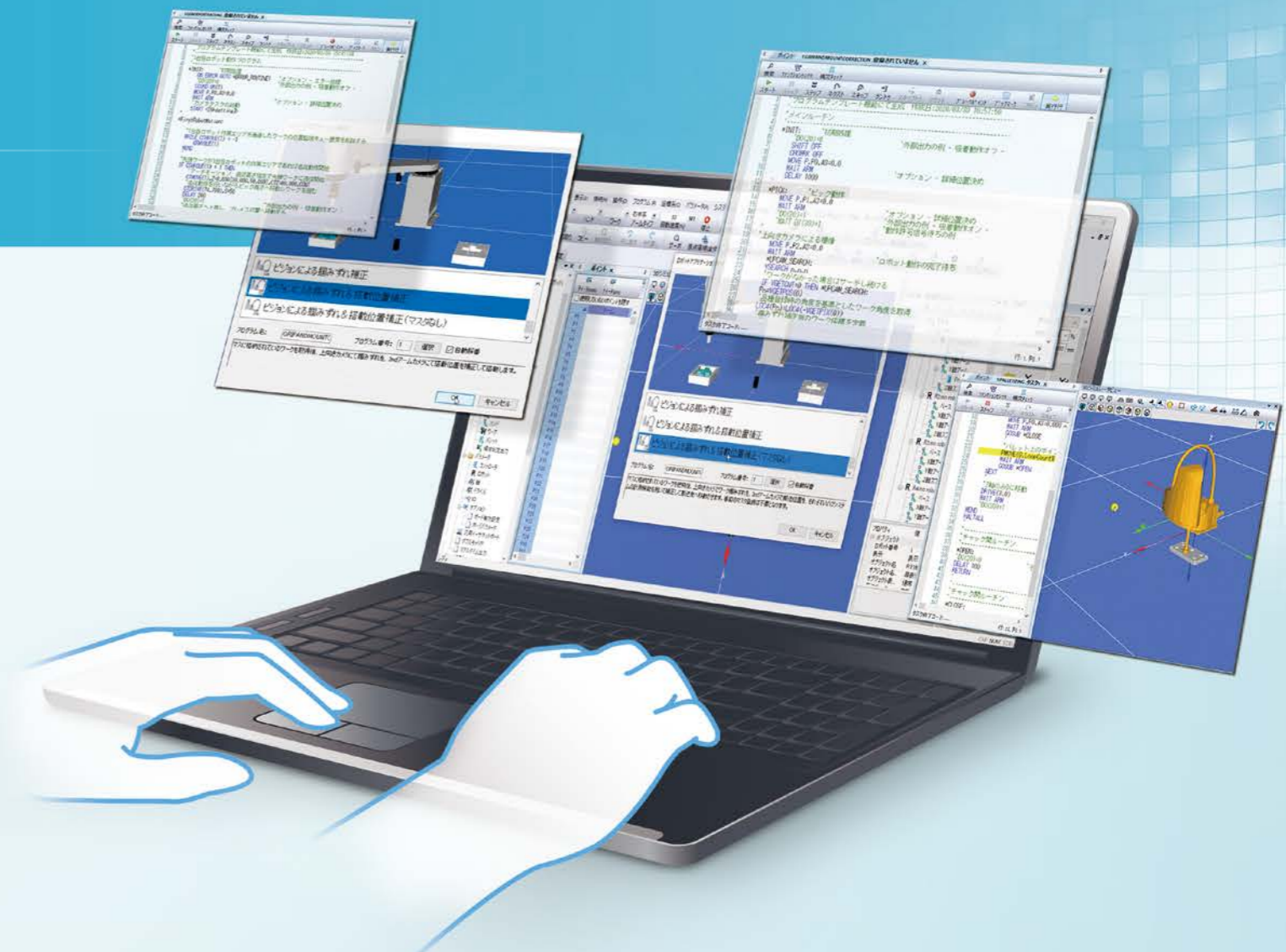
● Pallet picking using vision



● Parts orientation adjustment on the fly with vision



● Switching execution program

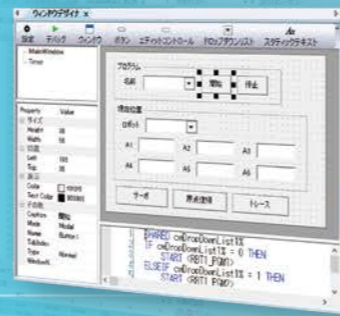


Programming process without command input to save time

# Customizing operation screen

## NEW Custom window creation

Easy creation of GUI for operators on PC



### Creating customized display on PC for operators

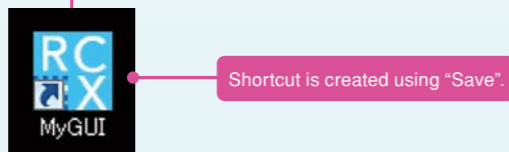
Existing window can be displayed.

- Servo
- Return-to-origin
- Point trace

Button press and timer cycle processes are described in robot language.

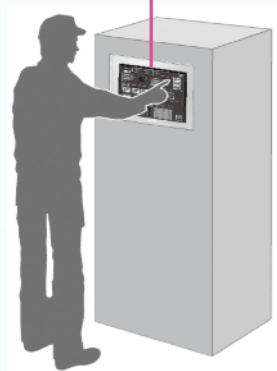
```

1 | SHARED cwDropDownList1%
2 | IF cwDropDownList1% = 0 THEN
3 |   START <RBT1_PGM>
4 | ELSEIF cwDropDownList1% = 1 THEN
5 |   START <RBT1_PGM>
    
```



### Operation screens for operators

Start by touching the dedicated shortcut.



Screen is started instead of Studio.

Studio's existing window display

Functions necessary for operation can be narrowed down. Operation screens suitable for the customer's equipment can be created to prevent troubles such as data erasing or rewriting due to misoperation.

Abundant functions that are succeeded from "RCX-Studio Pro" support the YAMAHA robot operation from the startup to the maintenance work.

Pre-investigation before purchase

Parallel setup after delivery

Preceding start before delivery

Software improvement investigation after operation start



### Functions succeeded from "RCX-Studio Pro".

#### ▶ Cycle time calculation

Cycle time between two points is calculated simply only with two steps. By entering a robot model and position data, it will calculate the cycle time.

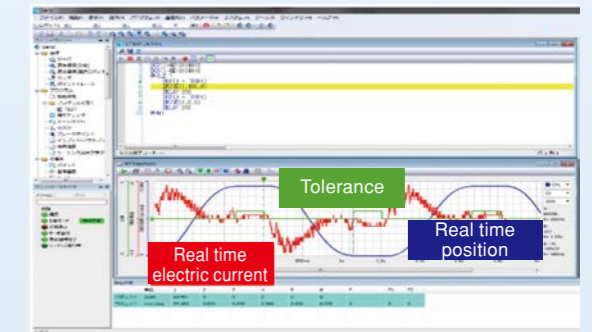
軸	A1	A2	A3	A4
スタート位置 (mm)	242	211	241	241
スタート速度 (mm/s)	30000	30000	2000	30000
到達位置 (mm)	8000	8000	1800	30000
到達速度 (mm/s)	1000	1000	8000	10000
到達加速度 (mm/s <sup>2</sup> )	100	100	7000	10000
戻り速度 (mm/s)	0	0	0	0
戻り加速度 (mm/s <sup>2</sup> )	0	0	0	0
戻り減速度 (mm/s <sup>2</sup> )	0	0	0	0

#### ▶ Real time trace

Internal information on the controller is output continuously. Robot status can be checked in real time.

##### Obtainable data

- I/O status
- Programming task status
- Task number being executed
- Controller temperature
- Driver status
  - Tolerance, out effective position, command position, current position, command speed, current speed, command current, present current, motor load factor, driver load factor



#### ▶ Data comparison

Difference between two specified data is displayed visually. Direct comparison with the online data can be performed to greatly reduce the maintenance time.

2 data is selected to compare them.

## ◆ Specifications

MEMO

### Software

Software can be downloaded from YAMAHA's WEB site together with RCX-Studio 2020 Basic or RCX-Studio 2020 Pro.



### Basic specifications

Product name	RCX-Studio 2020 Basic	RCX-Studio 2020 Pro
Type <sup>Note1</sup>	KCX-M4990-40	KCX-M4990-50
License management	USB key (blue) <sup>Note2</sup>	USB key (purple)
Supported language	Japanese, English, Chinese	
OS <sup>Note3</sup>	Microsoft Windows 7 SP1(32/64bit) / 8.1 (32 bit / 64 bit) / 10 (32 bit / 64 bit)	
Execution environment	.NET Framework 4.5 or more	
CPU	Recommended: Intel Core i5 2 GHz or more, Minimum: Intel Celeron 2 GHz or more, 3D-SIM is invalid.: Intel Core 2 Duo 2 GHz or more	
Memory	Recommended: 8 GB or more, Minimum: 4 GB or more, 3D-SIM is invalid: 1 GB or more	
Hard disk capacity	1GB of available space required on installation drive	
Communication Port	Communication cable: Serial communication port, Ethernet port, or USB port	
Others	Dedicated commutation cable (For D-Sub or USB) Ethernet cable (category 5 or better) USB port: 1 port (For USB key)	
Applicable controller	RCX340/RCX320	
Applicable robot	YAMAHA robot that can be connected to the RCX340, RCX320.	

Note1. This shows the software package type. The software is common to two products and can be downloaded from YAMAHA's WEB site.

Note2. Common to the conventional model RCX-Studio Pro.

Note3. Microsoft, Windows 7, Windows 8.1, and Windows 10 are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

Other company names and product names listed in this manual may be the trademarks or registered trademarks of their respective companies.

### Data cables (5m)

Communication cable for RCX-Studio 2020.

Select from USB cable or D-sub cable.

Model	USB type (5m)	KBG-M538F-00
	D-Sub type 9pin-9pin (5m)	KAS-M538F-10



**Ethernet cable  
(category 5 or higher)  
is also supported.**

Note. This USB cable supports Windows 2000/XP or later.

Note. The communication cable is common to POPCOM+, VIP+, RCX-Studio Pro, and RCX-Studio 2020.

Note. USB driver for communication cable can also be downloaded from our website.

### USB key

A USB key is supplied to the RCX-Studio 2020 to prevent irregular movement of robots.

There will be limitations of software functions (see below chart):

Functions		When the USB key is not connected	RCX-Studio 2020 Basic (blue) <sup>Note.</sup>	RCX-Studio 2020 Pro (purple) <sup>Note.</sup>
Backup/restore via data transfer		Valid	Valid	Valid
Controller operation in online mode		Invalid	Valid	Valid
File save		Invalid	Valid	Valid
Real Time Trace		Only data save is invalid.	Valid	Valid
Cycletime Calculator		Starting only (No calculating)	Valid	Valid
iVY2 editor		Starting only (No connecting)	Valid	Valid
Data Difference		Except data saving	Valid	Valid
3D simulator function		Only capturing is invalid.	Valid	Valid
Custom window		Valid	Valid	Valid
Program template		Only file output is invalid.	Valid	Valid
CAD data read	STL, OBJ, VRML	Valid	Valid	Valid
	STEP	Invalid	Invalid	Valid
CAD to point conversion		Invalid	Invalid	Valid

Note. USB key color



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**URL** <https://global.yamaha-motor.com/business/robot/>  
**E-MAIL** [robotn@yamaha-motor.co.jp](mailto:robotn@yamaha-motor.co.jp)

● Specifications and appearance are subject to change without prior notice.

202006-AE